

## 40-W MONO CLASS-D AUDIO POWER AMPLIFIER

### FEATURES

- 40-W Into an 8-Ω Load From a 25-V Supply
- Operates From 10 V to 26 V
- Efficient Class-D Operation Eliminates the Need for Heat Sinks
- Four Selectable, Fixed Gain Settings
- Differential Inputs
- Thermal and Short-Circuit Protection With Auto Recovery Feature
- Clock Output for Synchronization With Multiple Class-D Devices
- Surface Mount 7×7, 32-pin HLQFP Package

### APPLICATIONS

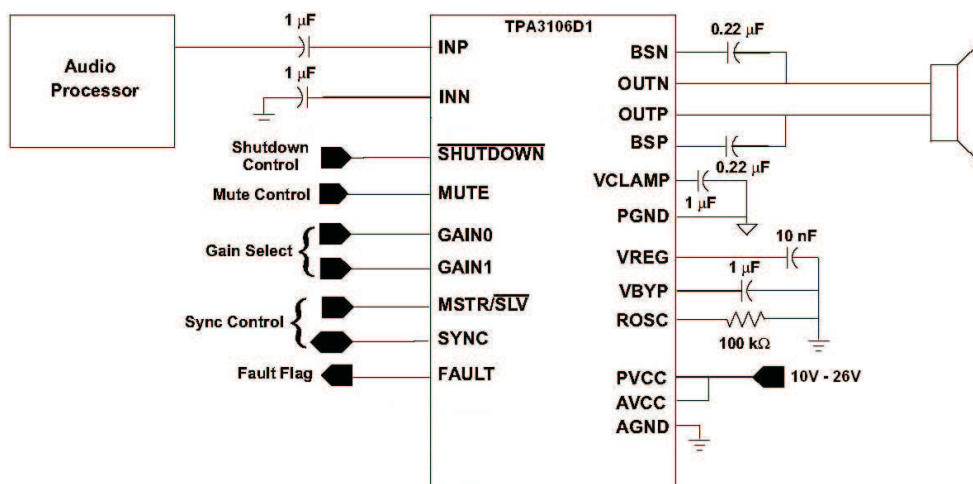
- Televisions
- Powered Speakers

### DESCRIPTION

The TPA3106D1 is a 40-W efficient, Class-D audio power amplifier for driving bridged-tied stereo speakers. The TPA3106D1 can drive stereo speakers as low as 4Ω. The high efficiency, ~92%, of the TPA3106D1 eliminates the need for an external heat sink when playing music.

The gain of the amplifier is controlled by two gain select pins. The gain selections are 20, 26, 32, 36 dB.

The outputs are fully protected against shorts to GND,  $V_{CC}$ , and output-to-output shorts with an auto recovery feature and monitor output.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

## ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		UNIT
V <sub>CC</sub>	Supply voltage	AVCC, PVCC
		–0.3 V to 30 V
V <sub>I</sub>	Input voltage	SHUTDOWN, MUTE
		GAIN0, GAIN1, INN, INP, MSTR/SLV, SYNC
		–0.3 V to V <sub>CC</sub> + 0.3 V
		–0.3 V to VREG + 0.5 V
Continuous total power dissipation		See Dissipation Rating Table
T <sub>A</sub>	Operating free-air temperature range	–40°C to 85°C
T <sub>J</sub>	Operating junction temperature range <sup>(2)</sup>	–40°C to 150°C
T <sub>stg</sub>	Storage temperature range	–65°C to 150°C
Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds		260°C
R <sub>Load</sub>	Load resistance	3.2 Ω Minimum
Electrostatic discharge	Human body model <sup>(3)</sup> (all pins)	
	Charged-device model <sup>(4)</sup> (all pins)	
		±2 kV
		±500 V

- Stresses beyond those listed under *absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only, and functional operations of the device at these or any other conditions beyond those indicated under *recommended operating conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- The TPA3106D1 incorporates an exposed thermal pad on the underside of the chip. This acts as a heatsink, and it must be connected to a thermally dissipating plane for proper power dissipation. Failure to do so may result in the device going into thermal protection shutdown. See TI Technical Briefs [SCBA017D](#) and [SLUA271](#) for more information about using the QFN thermal pad. See TI Technical Briefs [SLMA002](#) for more information about using the HTQFP thermal pad.
- In accordance with JEDEC Standard 22, Test Method A114-B.
- In accordance with JEDEC Standard 22, Test Method C101-A.

## TYPICAL DISSIPATION RATINGS

PACKAGE <sup>(1)</sup>	T <sub>A</sub> ≤ 25°C	DERATING FACTOR	T <sub>A</sub> = 70°C	T <sub>A</sub> = 85°C
32-pin VFP (HLQFP)	3.57 W	29 mW/°C <sup>(2)</sup>	2.29 W	1.86 W

- For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI Web site at [www.ti.com](http://www.ti.com). See TI Technical Briefs [SCBA017D](#) and [SLUA271](#) for more information about using the QFN thermal pad.
- This data was taken using a 2 oz trace and copper pad that is soldered directly to a 2-layer high-k PCB (EVM) and they are typical values. The thermal pad must be soldered to a thermal land on the printed-circuit board. See TI Technical Briefs [SLMA002](#) for more information about using the HLQFP thermal pad.

## RECOMMENDED OPERATING CONDITIONS

over operating free-air temperature range (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT	
V <sub>CC</sub>	Supply voltage	PVCC, AVCC	10	26	V
V <sub>IH</sub>	High-level input voltage	SHUTDOWN, MUTE, GAIN0, GAIN1, MSTR/SLV, SYNC	2		V
V <sub>IL</sub>	Low-level input voltage	SHUTDOWN, MUTE, GAIN0, GAIN1, MSTR/SLV, SYNC		0.8	V
I <sub>IH</sub>	High-level input current	SHUTDOWN, V <sub>I</sub> = V <sub>CC</sub> , V <sub>CC</sub> = 24 V		125	μA
		MUTE, V <sub>I</sub> = V <sub>CC</sub> , V <sub>CC</sub> = 24 V		75	
		GAIN0, GAIN1, MSTR/SLV, SYNC, V <sub>I</sub> = VREG, V <sub>CC</sub> = 24 V		2	
I <sub>IL</sub>	Low-level input current	SHUTDOWN, V <sub>I</sub> = 0, V <sub>CC</sub> = 24 V		2	μA
		SYNC, MUTE, GAIN0, GAIN1, MSTR/SLV, V <sub>I</sub> = 0 V, V <sub>CC</sub> = 24 V		1	
V <sub>OH</sub>	High-level output voltage	FAULT, I <sub>OH</sub> = 1 mA	VREG – 0.6		V
V <sub>OL</sub>	Low-level output voltage	FAULT, I <sub>OL</sub> = -1 mA		AGND + 0.4	V
f <sub>OSC</sub>	Oscillator frequency	R <sub>OSC</sub> resistor = 100 kΩ	200	300	kHz
T <sub>A</sub>	Operating free-air temperature		–40	85	°C

## DC CHARACTERISTICS

 $T_A = 25^\circ\text{C}$ ,  $V_{CC} = 24\text{ V}$ ,  $R_L = 8\ \Omega$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
V <sub>OS</sub>	Class-D output offset voltage (measured differentially)	V <sub>I</sub> = 0 V, Gain = 36 dB		5	50	mV	
	Bypass reference for input amplifier	VBYP, no load	1.2	1.35	1.55	V	
	4-V internal supply voltage	VREG, no load, V <sub>CC</sub> = 10 V to 26 V	3.8	4.1	4.4	V	
PSRR	DC Power supply rejection ratio	V <sub>CC</sub> = 12 V to 24 V, inputs ac coupled to AGND, Gain = 36 dB		-70		dB	
I <sub>CC</sub>	Quiescent supply current	SHUTDOWN = 2 V, MUTE = 0 V, no load		14	17	mA	
I <sub>CC(SD)</sub>	Quiescent supply current in shutdown mode	SHUTDOWN = 0.8 V, no load		215	250	μA	
I <sub>CC(MUTE)</sub>	Quiescent supply current in mute mode	MUTE = 2 V, no load		6	9	mA	
r <sub>DS(on)</sub>	Drain-source on-state resistance	V <sub>CC</sub> = 12 V, I <sub>O</sub> = 500 mA, T <sub>J</sub> = 25°C	High Side	200		mΩ	
			Low side	200			
			Total	400	500		
G	Gain	GAIN1 = 0.8 V	GAIN0 = 0.8 V	19	20	21	dB
			GAIN0 = 2 V	25	26	27	
		GAIN1 = 2 V	GAIN0 = 0.8 V	31	32	33	dB
			GAIN0 = 2 V	35	36	37	
t <sub>ON</sub>	Turn-on time	C <sub>(VBYP)</sub> = 1 μF, SHUTDOWN = 2 V		25		ms	
t <sub>OFF</sub>	Turn-off time	C <sub>(VBYP)</sub> = 1 μF, SHUTDOWN = 0.8 V		0.1		ms	

## DC CHARACTERISTICS

 $T_A = 25^\circ\text{C}$ ,  $V_{CC} = 12\text{ V}$ ,  $R_L = 8\ \Omega$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
V <sub>OS</sub>	Class-D output offset voltage (measured differentially)	V <sub>I</sub> = 0 V, Gain = 36 dB		5	50	mV	
	Bypass reference for input amplifier	VBYP, no load	1.2	1.35	1.55	V	
	4-V internal supply voltage	VREG, no load	3.8	4.1	4.4	V	
PSRR	DC Power supply rejection ratio	V <sub>CC</sub> = 12 V to 24 V, Inputs ac coupled to AGND, Gain = 36 dB		-70		dB	
I <sub>CC</sub>	Quiescent supply current	SHUTDOWN = 2 V, MUTE = 0 V, no load		10	14	mA	
I <sub>CC(SD)</sub>	Quiescent supply current in shutdown mode	SHUTDOWN = 0.8 V, no load		130	180	μA	
I <sub>CC(MUTE)</sub>	Quiescent supply current in mute mode	MUTE = 2 V, no load		5	7	mA	
r <sub>DS(on)</sub>	Drain-source on-state resistance	V <sub>CC</sub> = 12 V, I <sub>O</sub> = 500 mA, T <sub>J</sub> = 25°C	High Side	200		mΩ	
			Low side	200			
			Total	400	500		
G	Gain	GAIN1 = 0.8 V	GAIN0 = 0.8 V	19	20	21	dB
			GAIN0 = 2 V	25	26	27	
		GAIN1 = 2 V	GAIN0 = 0.8 V	31	32	33	dB
			GAIN0 = 2 V	35	36	37	
t <sub>ON</sub>	Turn-on time	C <sub>(VBYP)</sub> = 1 μF, SHUTDOWN = 2 V		25		ms	
t <sub>OFF</sub>	Turn-off time	C <sub>(VBYP)</sub> = 1 μF, SHUTDOWN = 0.8 V		0.1		ms	

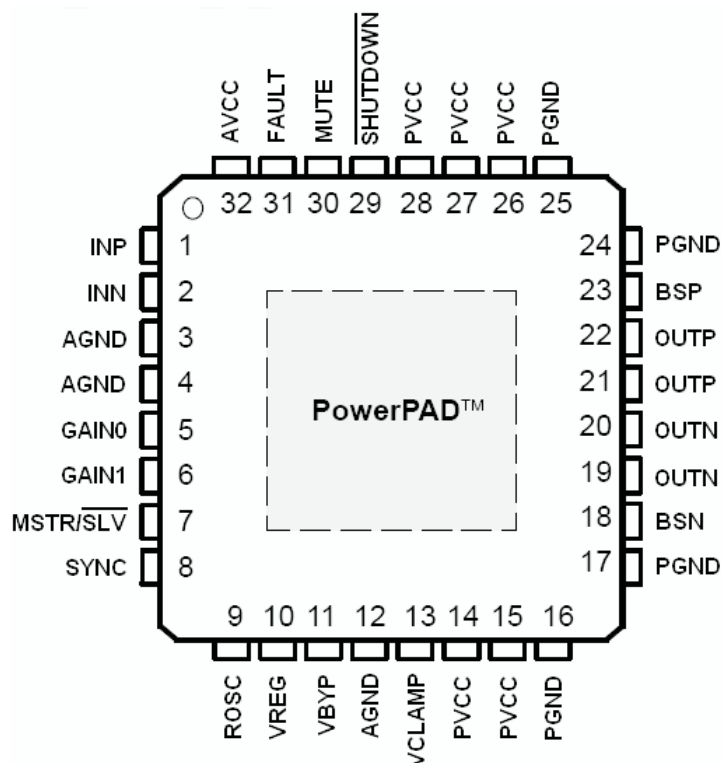
**AC CHARACTERISTICS**
 $T_A = 25^\circ\text{C}$ ,  $V_{CC} = 24\text{ V}$ ,  $R_L = 8\ \Omega$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$K_{SVR}$	Supply ripple rejection	200 mV <sub>PP</sub> ripple from 20 Hz–1 kHz, Gain = 20 dB, Inputs ac-coupled to AGND		–88		dB
$P_O$	Continuous output power	THD+N = 7%, f = 1 kHz, VCC = 24 V		32		W
		THD+N = 10%, f = 1 kHz, VCC = 24 V		40		
		THD+N < 7%, f = 1 kHz, VCC = 24 V, $R_L = 4\ \Omega$ , Thermally limited by package		25		
THD+N	Total harmonic distortion + noise	f = 1 kHz, $P_O = 20\text{ W}$ (half-power)		0.2%		
$V_n$	Output integrated noise	20 Hz to 22 kHz, A-weighted filter, Gain = 20 dB		125		$\mu\text{V}$
				–80		dBV
SNR	Signal-to-noise ratio	Maximum output at THD+N < 1%, f = 1 kHz, Gain = 20 dB, A-weighted		102		dB
	Thermal trip point			150		$^\circ\text{C}$
	Thermal hysteresis			30		$^\circ\text{C}$

**AC CHARACTERISTICS**
 $T_A = 25^\circ\text{C}$ ,  $V_{CC} = 12\text{ V}$ ,  $R_L = 8\ \Omega$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$K_{SVR}$	Supply ripple rejection	200 mV <sub>PP</sub> ripple from 20 Hz–1 kHz, Gain = 20 dB, Inputs ac-coupled to AGND		–88		dB
$P_O$	Continuous output power	THD+N = 7%, f = 1 kHz		8.7		W
		THD+N = 10%, f = 1 kHz		9.2		
		THD+N = 7%, f = 1 kHz, $R_L = 4\ \Omega$		15.6		
		THD+N = 10%, f = 1 kHz, $R_L = 4\ \Omega$		16.4		
THD+N	Total harmonic distortion + noise	$R_L = 8\ \Omega$ , f = 1 kHz, $P_O = 5\text{ W}$		0.11%		
		$R_L = 4\ \Omega$ , f = 1 kHz, $P_O = 8\text{ W}$		0.15%		
$V_n$	Output integrated noise	20 Hz to 22 kHz, A-weighted filter, Gain = 20 dB		100		$\mu\text{V}$
				–80		dBV
SNR	Signal-to-noise ratio	Maximum output at THD+N < 1%, f = 1 kHz, Gain = 20 dB, A-weighted		98		dB
	Thermal trip point			150		$^\circ\text{C}$
	Thermal hysteresis			30		$^\circ\text{C}$

32-PIN HTQFP (VFP)  
(TOP VIEW)



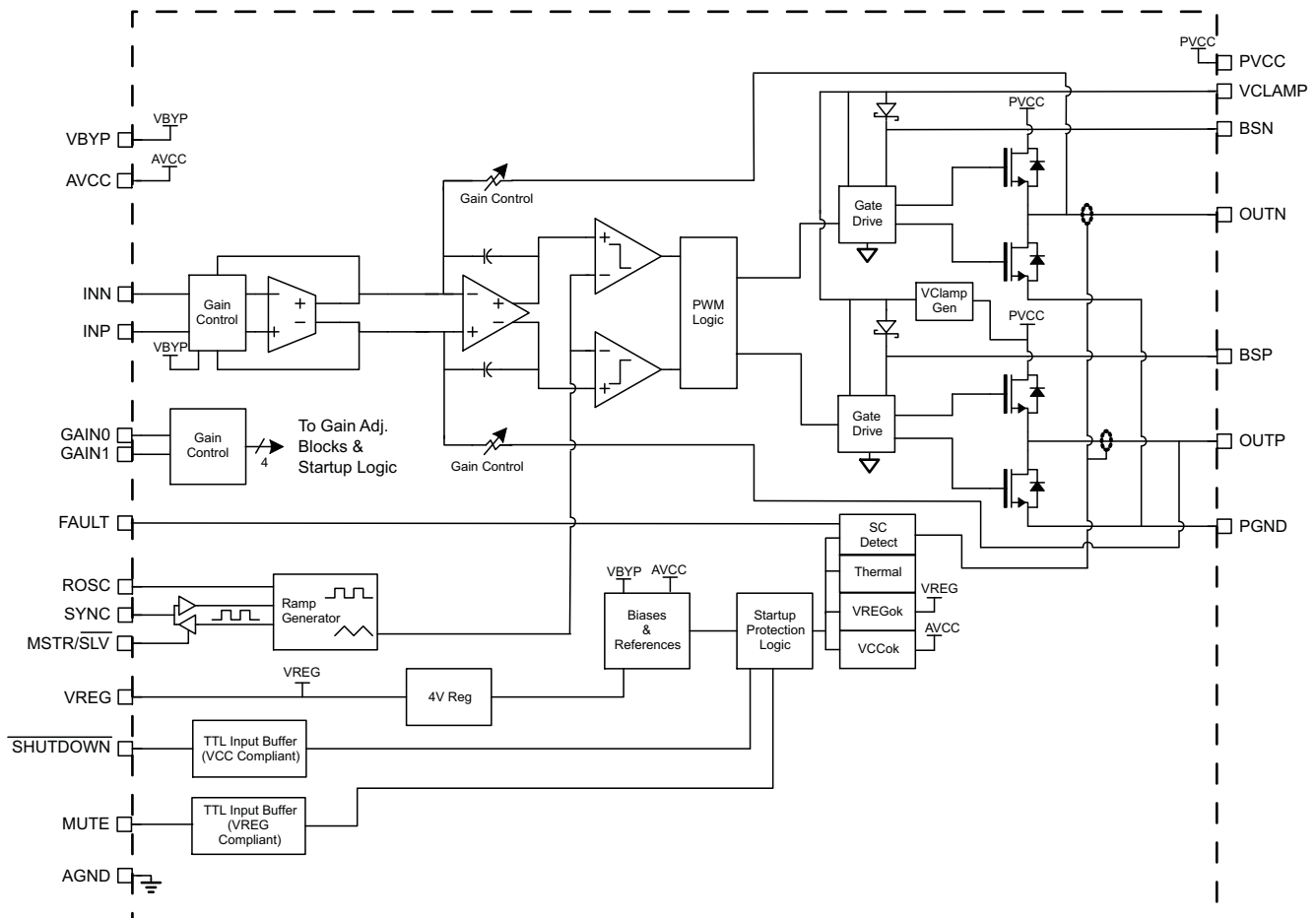
### TERMINAL FUNCTIONS

TERMINAL		I/O	DESCRIPTION
NAME	NO.		
SHUTDOWN	29	I	Active low. Shutdown signal for IC (LOW = disabled, HIGH = operational). TTL logic levels with compliance to AVCC.
INN	1	I	Negative audio input
INP	2	I	Positive audio input
GAIN0	5	I	Gain select least significant bit. TTL logic levels with compliance to VREG.
GAIN1	6	I	Gain select most significant bit. TTL logic levels with compliance to VREG.
MUTE	30	I	Active high. Mute signal for quick disable/enable of outputs (HIGH = outputs high-Z, LOW = outputs enabled). TTL logic levels with compliance to AVCC.
FAULT	31	O	TTL compatible output. HIGH = short-circuit fault. LOW = no fault. Only reports short-circuit faults. Thermal faults are not reported on this terminal.
BSP	23	I/O	Bootstrap I/O for left channel, positive high-side FET.
PVCC	14, 15, 26–28		Power supply for left channel H-bridge, not internally connected to AVCC.
OUTPUT	21, 22	O	Class-D 1/2-H-bridge positive output
PGND	16, 17, 24, 25		Power ground for H-bridge.
OUTN	19, 20	O	Class-D 1/2-H-bridge negative output
BSN	18	I/O	Bootstrap I/O for left channel, negative high-side FET.
VCLAMP	13		Internally generated voltage supply for bootstrap capacitor.
AGND	3, 4, 12		Analog ground for digital/analog cells in core.
ROSC	9	I/O	I/O for current setting resistor of ramp generator.

**TERMINAL FUNCTIONS (continued)**

TERMINAL		I/O	DESCRIPTION
NAME	NO.		
MSTR/ $\overline{\text{SLV}}$	7	I	Master/Slave select for determining direction of SYNC terminal. HIGH=Master mode, SYNC terminal is an output; LOW = slave mode, SYNC terminal accepts a clock input. TTL logic levels with compliance to VREG.
SYNC	8	I/O	Clock input/output for synchronizing multiple class-D devices. Direction determined by MSTR/ $\overline{\text{SLV}}$ terminal. Input signal not to exceed VREG.
VBYP	11	O	Reference for preamplifier. Nominally equal to 1.25 V. Also controls start-up time via external capacitor sizing.
VREG	10	O	4-V regulated output for use by internal cells, GAINx, MUTE, and MSTR/ $\overline{\text{SLV}}$ pins only. Not specified for driving other external circuitry.
AVCC	32		High-voltage analog power supply. Not internally connected to PVCC.
Thermal Pad	—	—	Connect to AGND and PGND – should be star point for both grounds. Internal resistive connection to AGND and PGND. Thermal vias on the PCB should connect this pad to a large copper area on an internal or bottom layer for the best thermal performance. <i>The Thermal Pad must be soldered to the PCB for mechanical reliability.</i>

**FUNCTIONAL BLOCK DIAGRAM**



## TYPICAL CHARACTERISTICS

### TABLE OF GRAPHS

Y-AXIS	X-AXIS	FIGURE
Total Harmonic Distortion + N (%)	Frequency (Hz) (BTL)	<a href="#">Figure 1</a>
Total Harmonic Distortion + N (%)	Frequency (Hz) (BTL)	<a href="#">Figure 2</a>
Total Harmonic Distortion + N (%)	Frequency (Hz) (BTL)	<a href="#">Figure 3</a>
Total Harmonic Distortion + N (%)	Frequency (Hz) (BTL)	<a href="#">Figure 4</a>
Total Harmonic Distortion + N (%)	Frequency (Hz) (BTL)	<a href="#">Figure 5</a>
Total Harmonic Distortion + N (%)	Frequency (Hz) (BTL)	<a href="#">Figure 6</a>
Total Harmonic Distortion + N (%)	Output Power (W) (BTL)	<a href="#">Figure 7</a>
Total Harmonic Distortion + N (%)	Output Power (W) (BTL)	<a href="#">Figure 8</a>
Total Harmonic Distortion + N (%)	Output Power (W) (BTL)	<a href="#">Figure 9</a>
Total Harmonic Distortion + N (%)	Output Power (W) (BTL)	<a href="#">Figure 10</a>
Total Harmonic Distortion + N (%)	Output Power (W) (BTL)	<a href="#">Figure 11</a>
Total Harmonic Distortion + N (%)	Output Power (W) (BTL)	<a href="#">Figure 12</a>
Closed Loop Response	Frequency (Hz) (BTL)	<a href="#">Figure 13</a>
Closed Loop Response	Frequency (Hz) (BTL)	<a href="#">Figure 14</a>
$P_O$ – Output Power (W)	Supply Voltage (V) (BTL)	<a href="#">Figure 15</a>
$P_O$ – Output Power (W)	Supply Voltage (V) (BTL)	<a href="#">Figure 16</a>
Efficiency (%)	Output Power (W) (BTL)	<a href="#">Figure 16</a>
Efficiency (%)	Output Power (W) (BTL)	<a href="#">Figure 18</a>
Efficiency (%)	Output Power (W) (BTL)	<a href="#">Figure 19</a>
$I_{CC}$ – Supply Current (A)	$P_O$ – Total Output Power (W) (BTL)	<a href="#">Figure 20</a>
$I_{CC}$ – Supply Current (A)	$P_O$ – Total Output Power (W) (BTL)	<a href="#">Figure 21</a>
$k_{SVR}$ – Supply Rejection Ratio (dB)	Frequency (Hz) (BTL)	<a href="#">Figure 22</a>
$k_{SVR}$ – Supply Rejection Ratio (dB)	Frequency (Hz) (BTL)	<a href="#">Figure 23</a>
$k_{SVR}$ – Supply Rejection Ratio (dB)	Frequency (Hz) (BTL)	<a href="#">Figure 24</a>

**TOTAL HARMONIC DISTORTION + NOISE  
vs  
FREQUENCY**

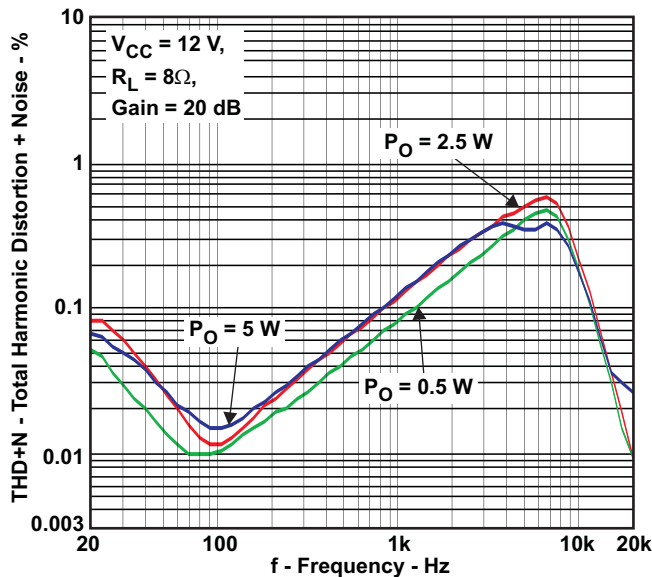


Figure 1.

**TOTAL HARMONIC DISTORTION + NOISE  
vs  
FREQUENCY**

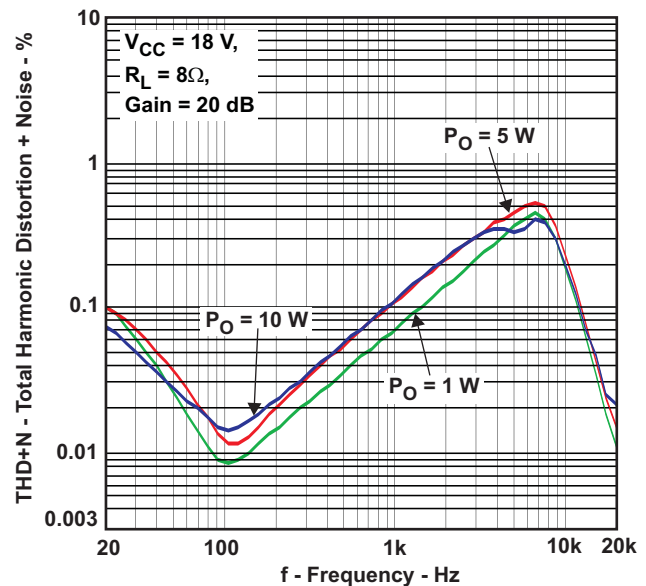


Figure 2.

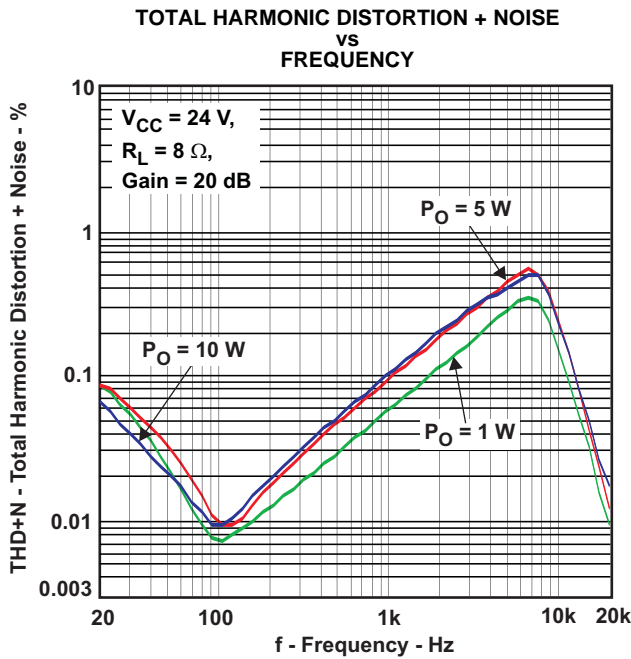


Figure 3.

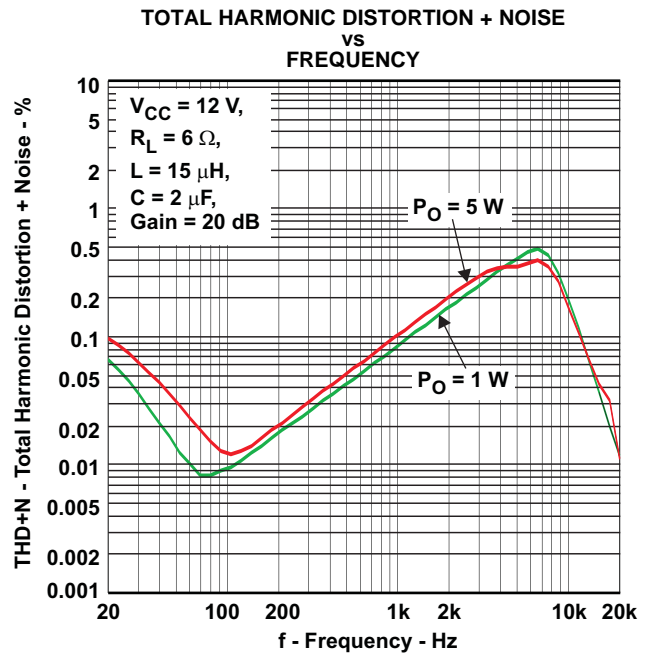


Figure 4.

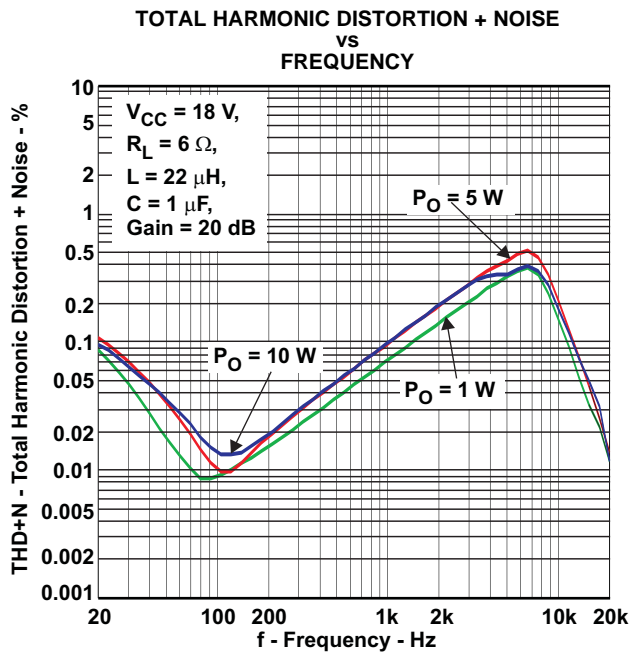


Figure 5.

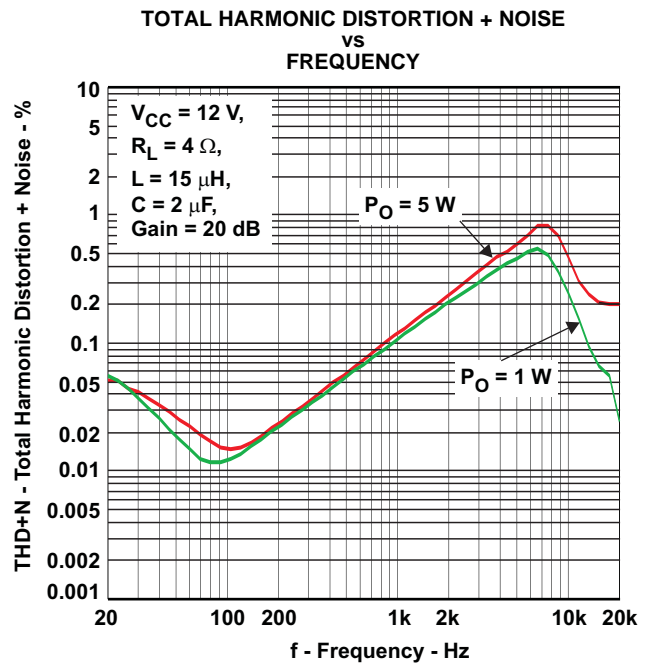


Figure 6.



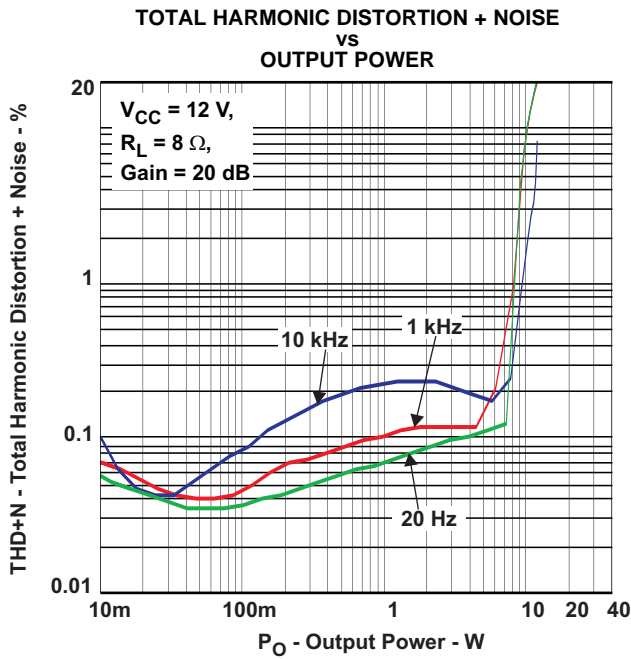


Figure 7.

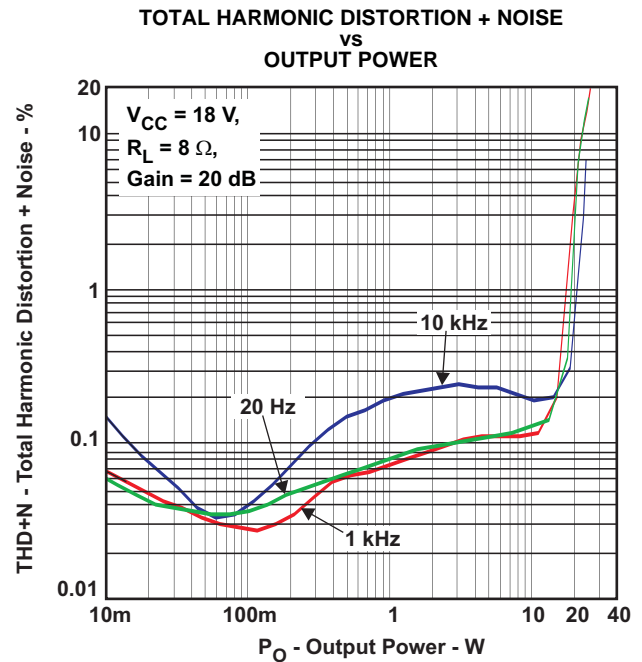


Figure 8.

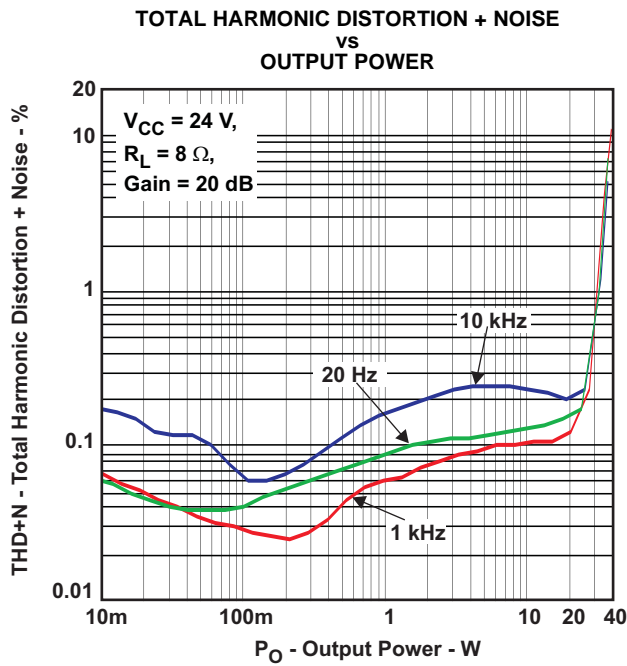


Figure 9.

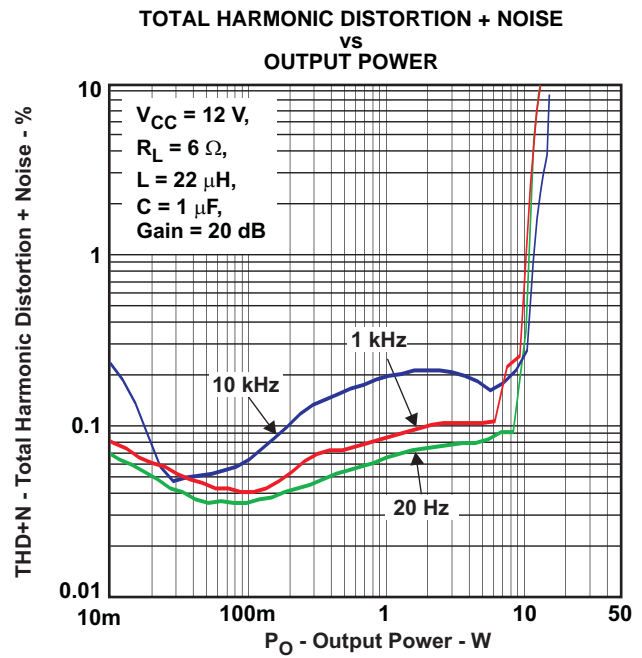


Figure 10.

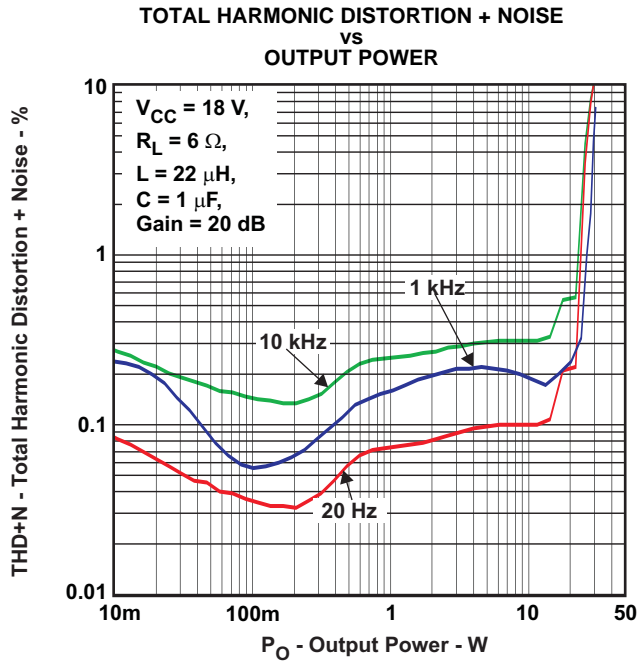


Figure 11.

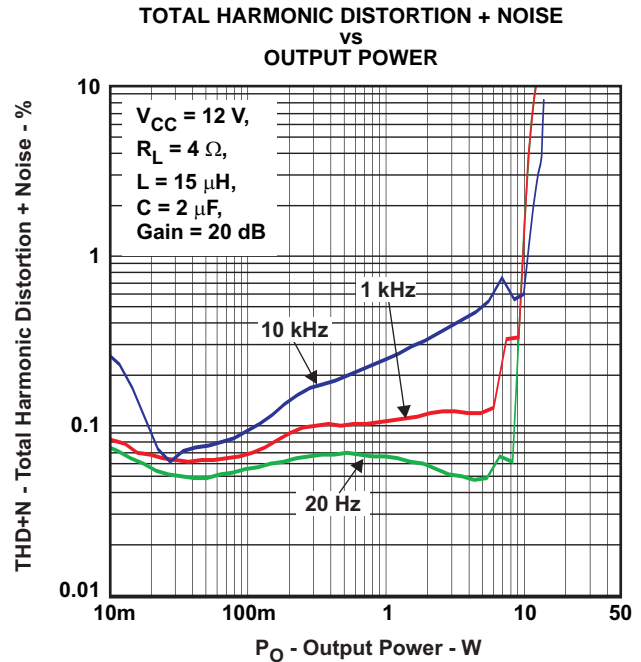


Figure 12.

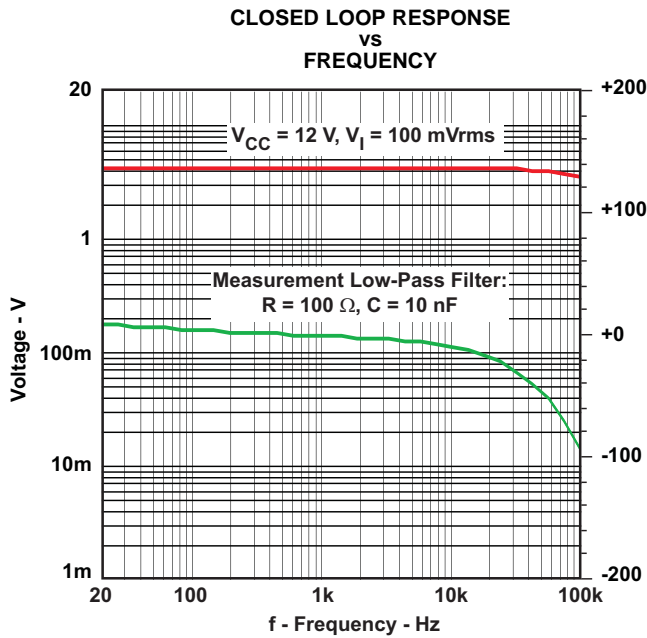


Figure 13.

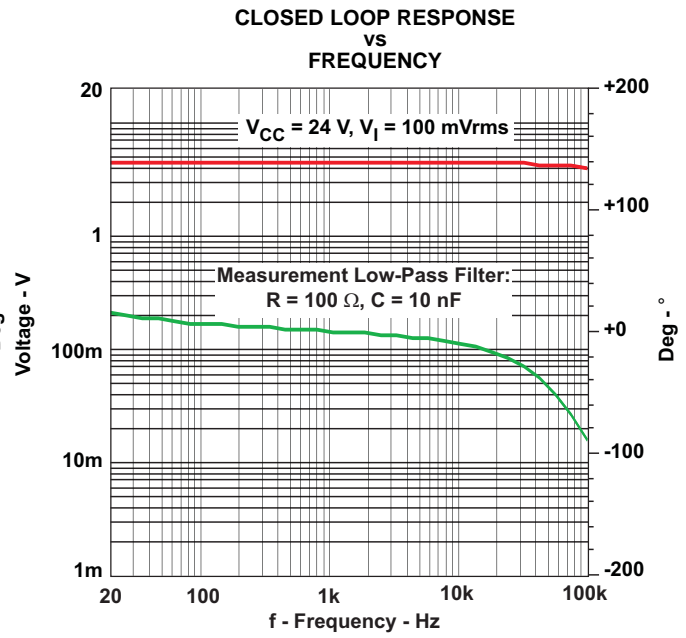


Figure 14.

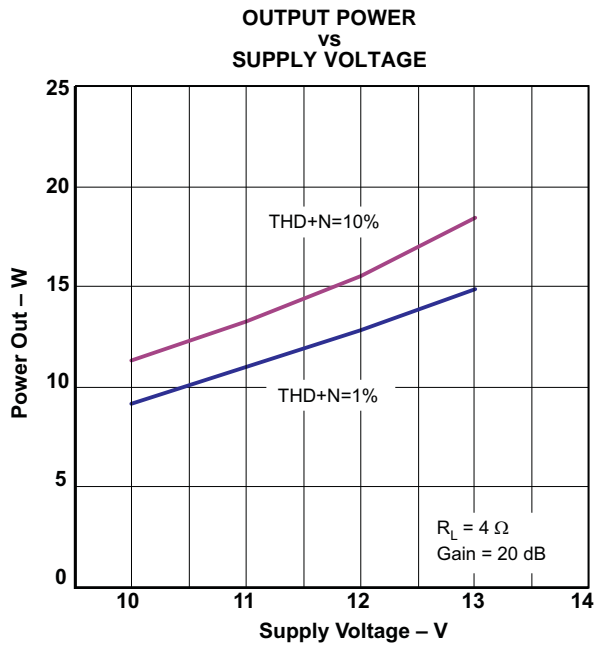


Figure 15.

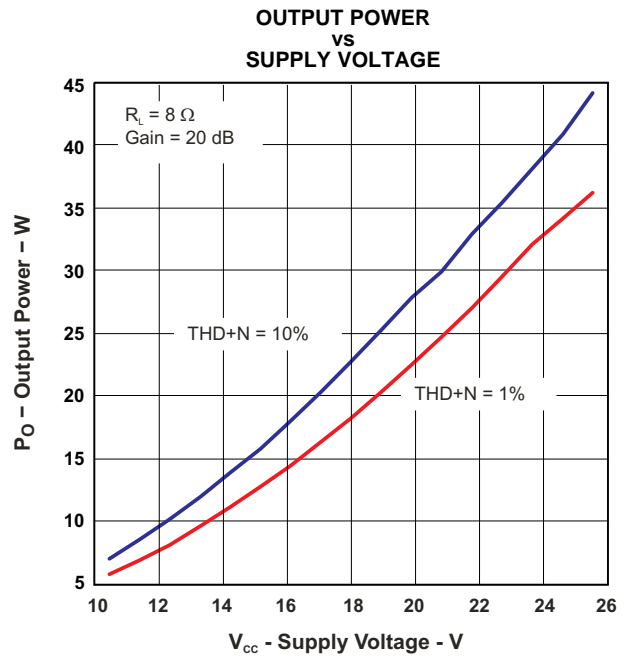


Figure 16.

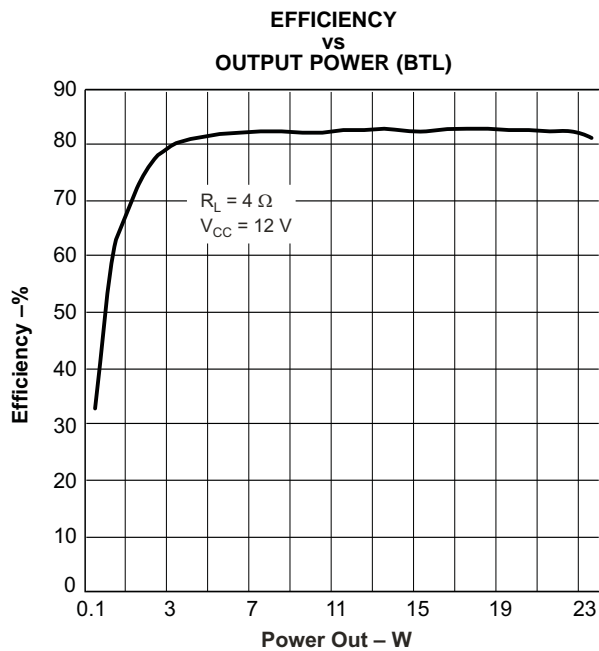


Figure 17.

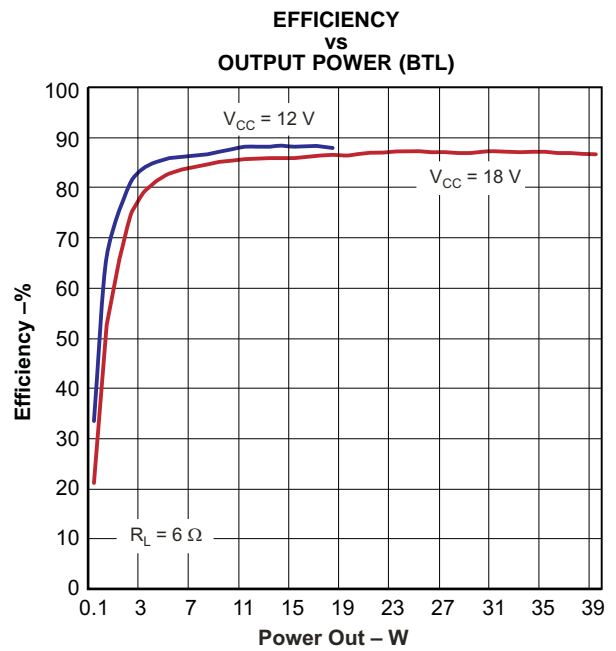


Figure 18.

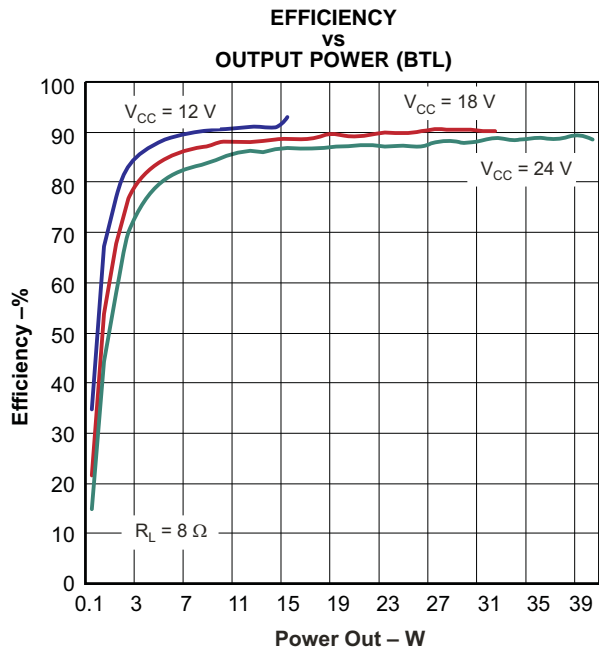


Figure 19.

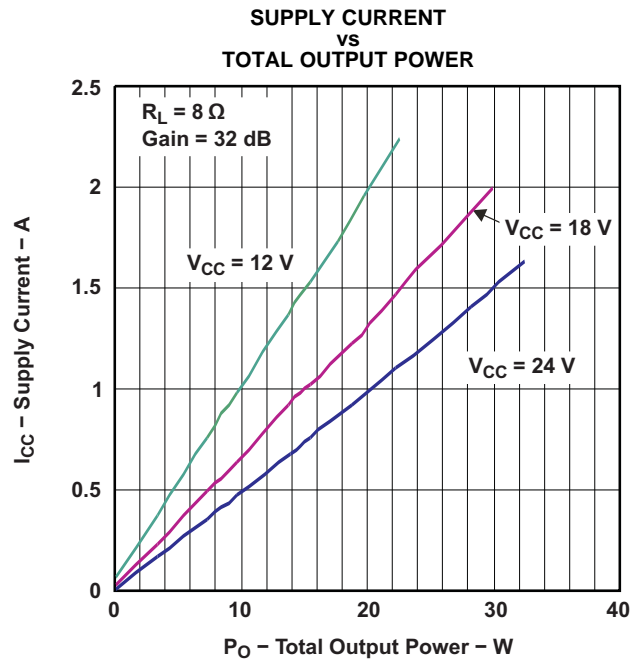


Figure 20.

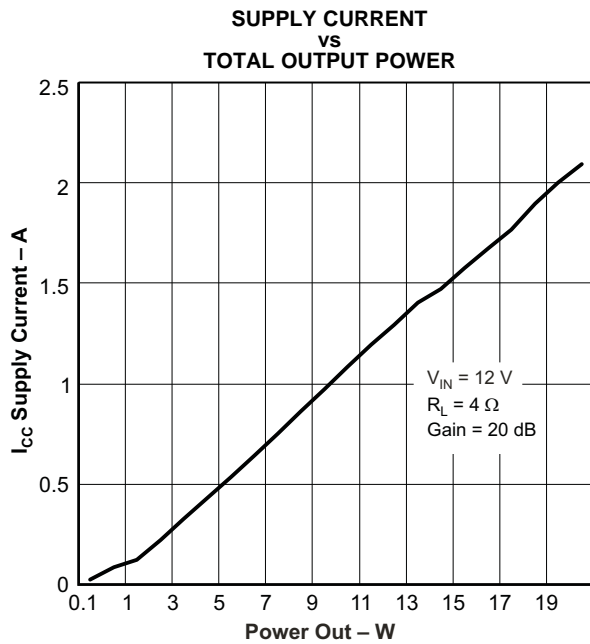


Figure 21.

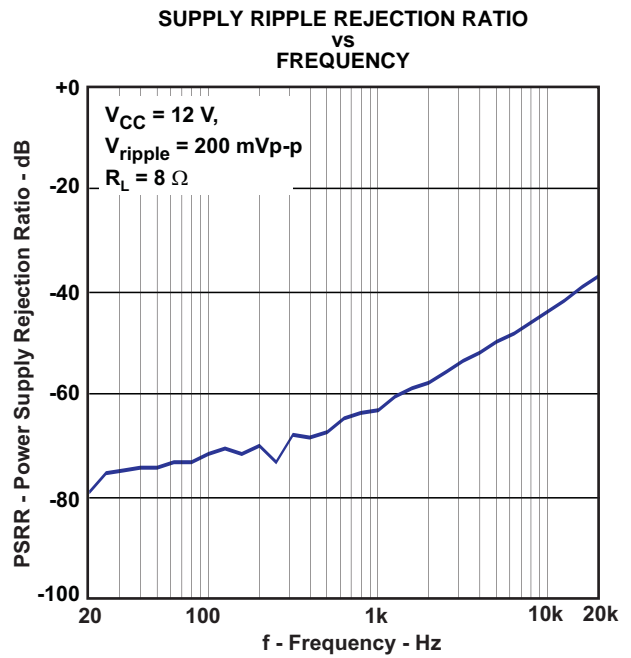


Figure 22.

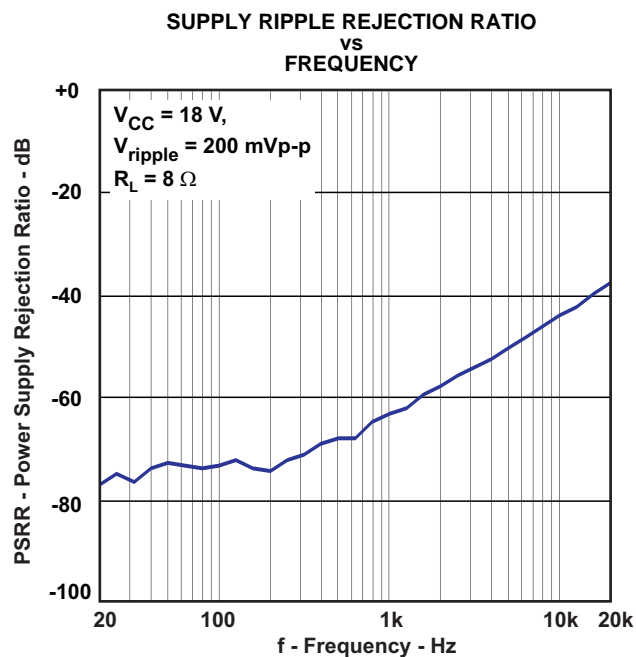


Figure 23.

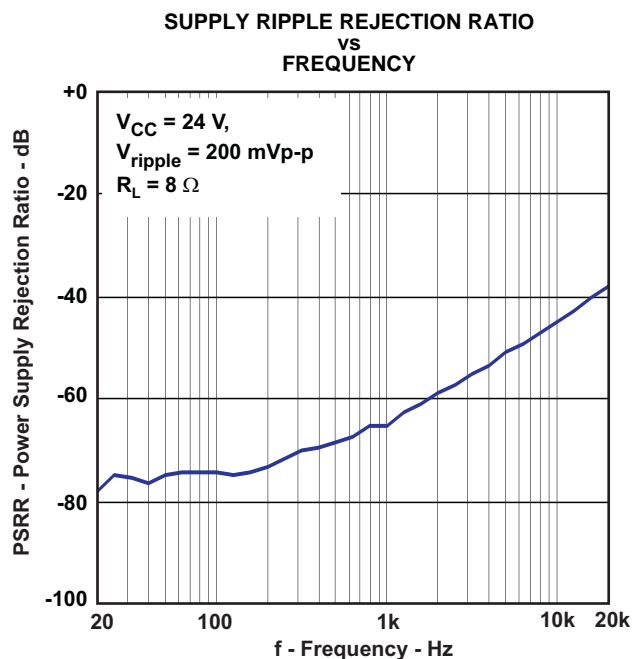


Figure 24.

APPLICATION INFORMATION

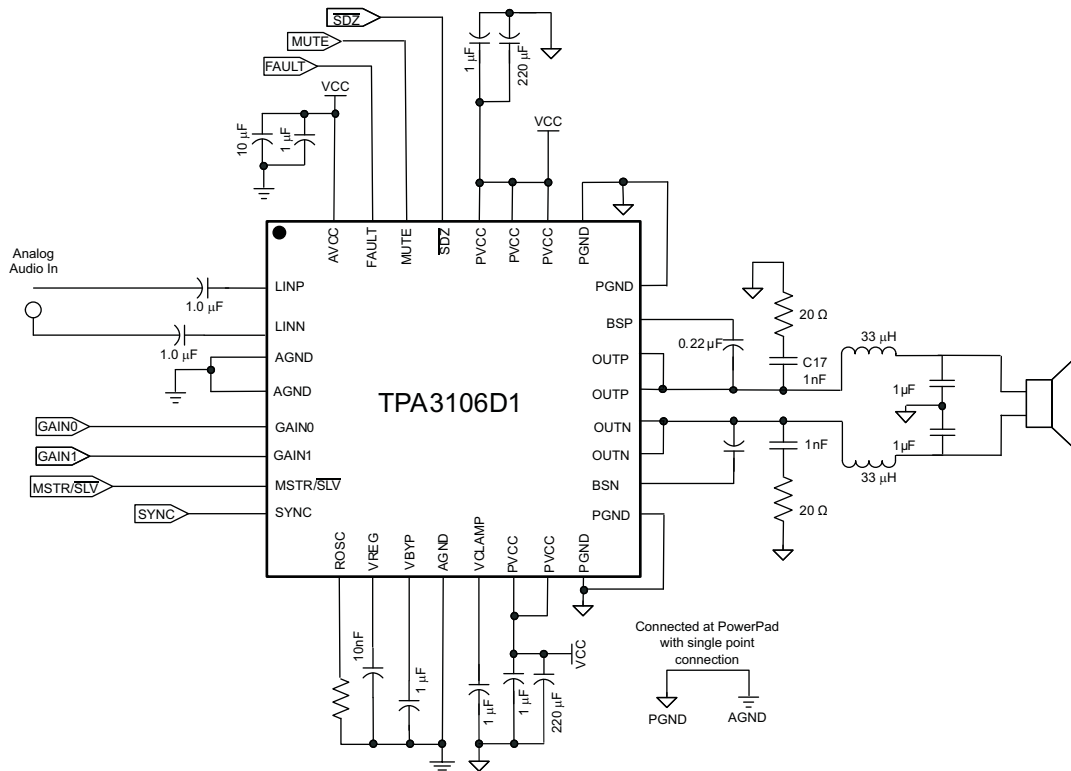


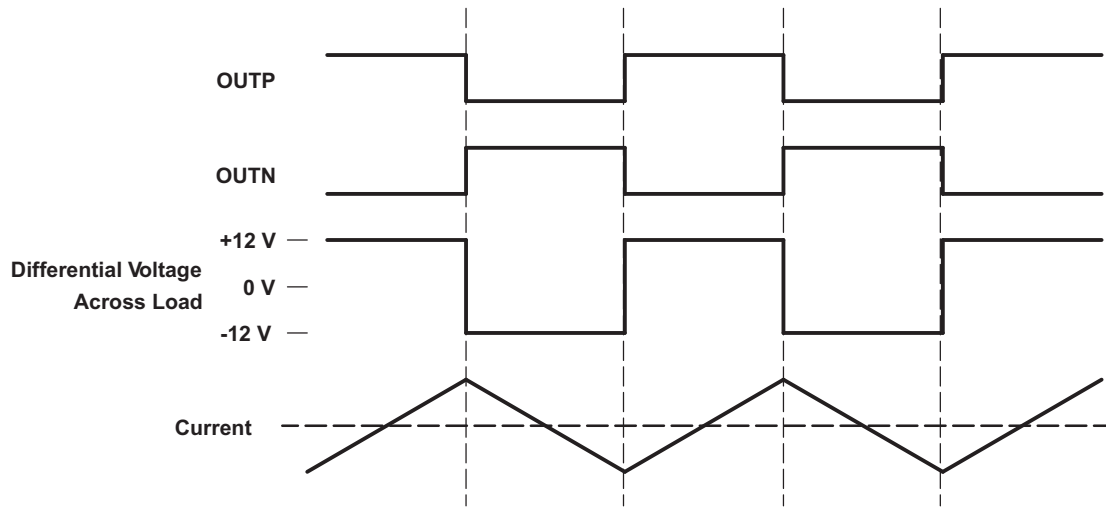
Figure 25. TPA3106D1 Application Circuit With Single-Ended Inputs

## CLASS-D OPERATION

This section focuses on the class-D operation of the TPA3106D1.

### Traditional Class-D Modulation Scheme

The traditional class-D modulation scheme, which is used in the TPA032D0x family, has a differential output where each output is 180 degrees out-of-phase and changes from ground to the supply voltage,  $V_{CC}$ . Therefore, the differential prefiltered output varies between positive and negative  $V_{CC}$ , where filtered 50% duty cycle yields 0 V across the load. The traditional class-D modulation scheme with voltage and current waveforms is shown in Figure 26. Note that even at an average of 0 V across the load (50% duty cycle), the current to the load is high, causing high loss and thus causing a high supply current.



**Figure 26. Traditional Class-D Modulation Scheme's Output Voltage and Current Waveforms into an Inductive Load With No Input**

### TPA3106D1 Modulation Scheme

The TPA3106D1 uses a modulation scheme that still has each output switching from 0 to the supply voltage. However, OUTP and OUTN are now in phase with each other with no input. The duty cycle of OUTP is greater than 50% and OUTN is less than 50% for positive output voltages. The duty cycle of OUTP is less than 50% and OUTN is greater than 50% for negative output voltages. The voltage across the load sits at 0 V throughout most of the switching period, greatly reducing the switching current, which reduces any  $I^2R$  losses in the load.

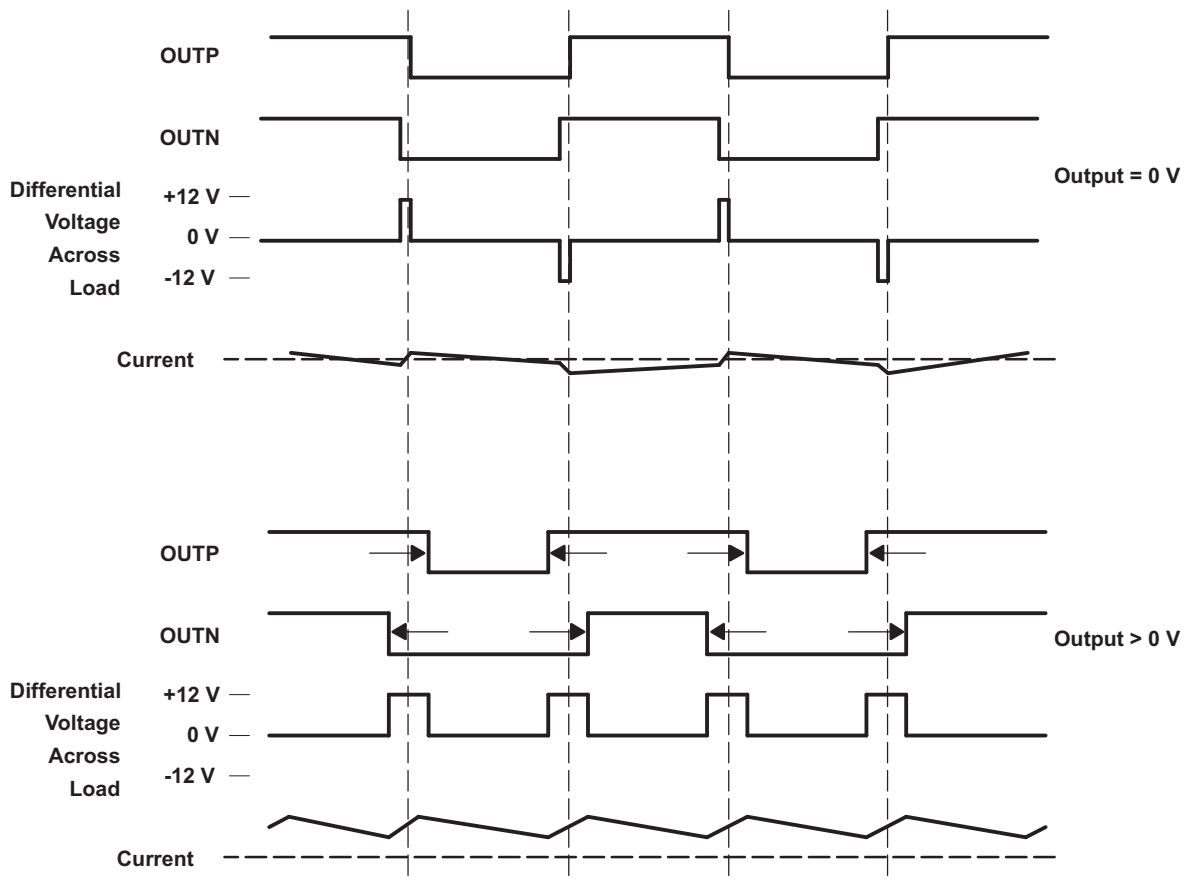


Figure 27. The TPA3100D2 Output Voltage and Current Waveforms Into an Inductive Load

### Efficiency: LC Filter Required With the Traditional Class-D Modulation Scheme

The main reason that the traditional class-D amplifier needs an output filter is that the switching waveform results in maximum current flow. This causes more loss in the load, which causes lower efficiency. The ripple current is large for the traditional modulation scheme, because the ripple current is proportional to voltage multiplied by the time at that voltage. The differential voltage swing is  $2 \times V_{CC}$ , and the time at each voltage is half the period for the traditional modulation scheme. An ideal LC filter is needed to store the ripple current from each half cycle for the next half cycle, while any resistance causes power dissipation. The speaker is both resistive and reactive, whereas an LC filter is almost purely reactive.

The TPA3106D1 modulation scheme has little loss in the load without a filter because the pulses are short and the change in voltage is  $V_{CC}$  instead of  $2 \times V_{CC}$ . As the output power increases, the pulses widen, making the ripple current larger. Ripple current could be filtered with an LC filter for increased efficiency, but for most applications the filter is not needed.

An LC filter with a cutoff frequency less than the class-D switching frequency allows the switching current to flow through the filter instead of the load. The filter has less resistance but higher impedance at the switching frequency than the speaker, which results in less power dissipation, therefore increasing efficiency.



## When to Use an Output Filter for EMI Suppression

Design the TPA3106D1 without the filter if the traces from amplifier to speaker are short (< 10 cm). Powered speakers, where the speaker is in the same enclosure as the amplifier, is a typical application for class-D without a filter.

Most applications require a ferrite bead filter. The ferrite filter reduces EMI around 1 MHz and higher (FCC and CE only test radiated emissions greater than 30 MHz). When selecting a ferrite bead, choose one with high impedance at high frequencies, but low impedance at low frequencies.

Use an LC output filter if there are low frequency (<1 MHz) EMI-sensitive circuits and/or there are long wires from the amplifier to the speaker.

When both an LC filter and a ferrite bead filter are used, the LC filter should be placed as close as possible to the IC followed by the ferrite bead filter.

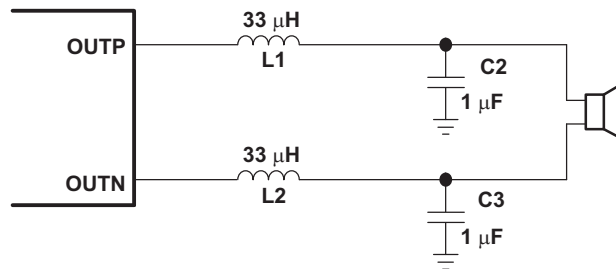


Figure 28. Typical LC Output Filter, Cutoff Frequency of 27 kHz, Speaker Impedance = 8  $\Omega$

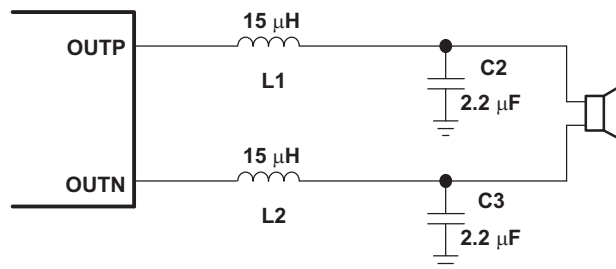


Figure 29. Typical LC Output Filter, Cutoff Frequency of 27 kHz, Speaker Impedance = 4  $\Omega$

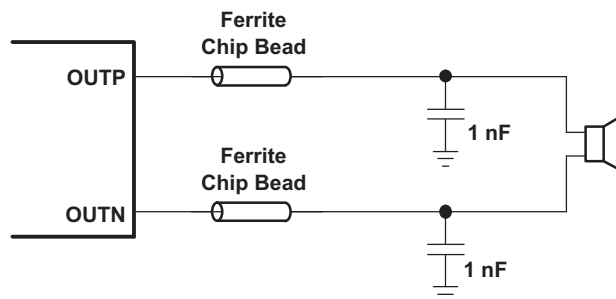


Figure 30. Typical Ferrite Chip Bead Filter (Chip Bead Example: Fair-Rite 2512067007Y3)

### Adaptive Dynamic Range Control

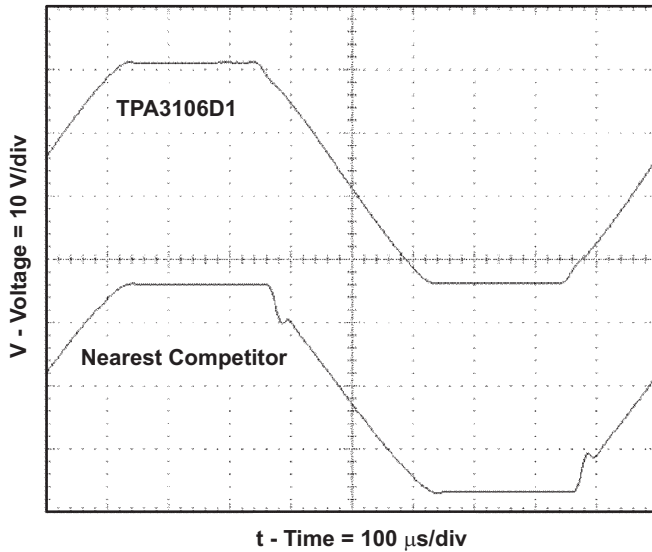


Figure 31. 1-kHz Sine Output at 10% THD+N

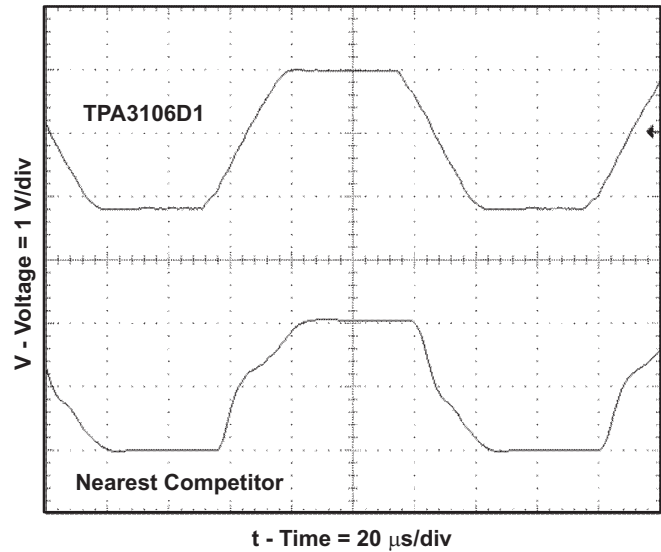


Figure 32. 8-kHz Sine Output at 10% THD+N

The Texas Instruments patent-pending adaptive dynamic range control (ADRC) technology removes the notch inherent in class-D audio power amplifiers when they come out of clipping. This effect is more severe at higher frequencies as shown in Figure 32.

### Gain Setting via GAIN0 and GAIN1 Inputs

The gain of the TPA3106D1 is set by two input terminals, GAIN0 and GAIN1.

The gains listed in Table 1 are realized by changing the taps on the input resistors and feedback resistors inside the amplifier. This causes the input impedance ( $Z_i$ ) to be dependent on the gain setting. The actual gain settings are controlled by ratios of resistors, so the gain variation from part-to-part is small. However, the input impedance from part-to-part at the same gain may shift by  $\pm 20\%$  due to shifts in the actual resistance of the input resistors.

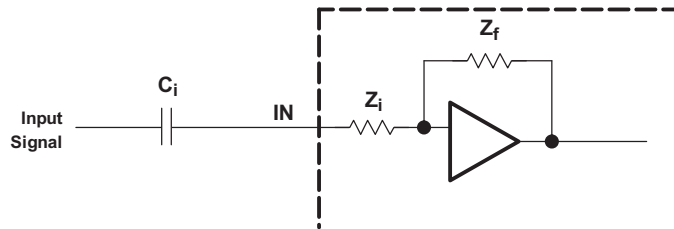
For design purposes, the input network (discussed in the next section) should be designed assuming an input impedance of 12.8 k $\Omega$ , which is the absolute minimum input impedance of the TPA3106D1. At the lower gain settings, the input impedance could increase as high as 38.4 k $\Omega$

Table 1. Gain Setting

GAIN1	GAIN0	AMPLIFIER GAIN (dB)	INPUT IMPEDANCE (k $\Omega$ )
		TYP	TYP
0	0	20	32
0	1	26	16
1	0	32	16
1	1	36	16

## INPUT RESISTANCE

Changing the gain setting can vary the input resistance of the amplifier from its smallest value, 16 kΩ ±20%, to the largest value, 32 kΩ ±20%. As a result, if a single capacitor is used in the input high-pass filter, the –3 dB or cutoff frequency may change when changing gain steps.

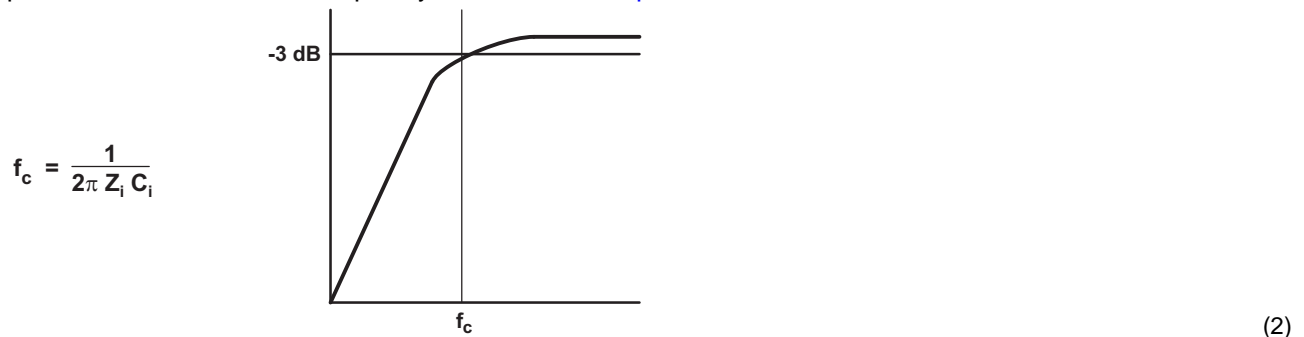


The –3-dB frequency can be calculated using Equation 1. Use the  $Z_i$  values given in Table 1.

$$f = \frac{1}{2\pi Z_i C_i} \quad (1)$$

## INPUT CAPACITOR, $C_i$

In the typical application, an input capacitor ( $C_i$ ) is required to allow the amplifier to bias the input signal to the proper dc level for optimum operation. In this case,  $C_i$  and the input impedance of the amplifier ( $Z_i$ ) form a high-pass filter with the corner frequency determined in Equation 2.



The value of  $C_i$  is important, as it directly affects the bass (low-frequency) performance of the circuit. Consider the example where  $Z_i$  is 20 kΩ and the specification calls for a flat bass response down to 20 Hz. Equation 2 is reconfigured as Equation 3.

$$C_i = \frac{1}{2\pi Z_i f_c} \quad (3)$$

In this example,  $C_i$  is 0.4 μF; so, one would likely choose a value of 0.47 μF as this value is commonly used. If the gain is known and is constant, use  $Z_i$  from Table 1 to calculate  $C_i$ . A further consideration for this capacitor is the leakage path from the input source through the input network ( $C_i$ ) and the feedback network to the load. This leakage current creates a dc offset voltage at the input to the amplifier that reduces useful headroom, especially in high gain applications. For this reason, a low-leakage tantalum or ceramic capacitor is the best choice. When polarized capacitors are used, the positive side of the capacitor should face the amplifier input in most applications as the dc level there is held at 2 V, which is likely higher than the source dc level. Note that it is important to confirm the capacitor polarity in the application. Additionally, lead-free solder can create dc offset voltages and it is important to ensure that boards are cleaned properly.

## Power Supply Decoupling, C<sub>s</sub>

The TPA3106D1 is a high-performance CMOS audio amplifier that requires adequate power supply decoupling to ensure that the output total harmonic distortion (THD) is as low as possible. Power supply decoupling also prevents oscillations for long lead lengths between the amplifier and the speaker. The optimum decoupling is achieved by using two capacitors of different types that target different types of noise on the power supply leads. For higher frequency transients, spikes, or digital hash on the line, a good low equivalent-series-resistance (ESR) ceramic capacitor, typically 0.1  $\mu\text{F}$  to 1  $\mu\text{F}$  placed as close as possible to the device  $V_{\text{CC}}$  lead works best. For filtering lower frequency noise signals, a larger aluminum electrolytic capacitor of 100  $\mu\text{F}$  per input lines (Pins 14, 15 and pins 26, 27, 28) or greater placed near the audio power amplifier is recommended. The 100  $\mu\text{F}$  capacitor also serves as local storage capacitor for supplying current during large signal transients on the amplifier outputs. The PVCC terminals provide the power to the output transistors, so a 100  $\mu\text{F}$  or larger capacitor should be placed on each PVCC terminal. A 10  $\mu\text{F}$  capacitor on the AVCC terminal is adequate.

The full H-bridge output stages use only NMOS transistors. Therefore, they require bootstrap capacitors for the high side of each output to turn on correctly. A 220-nF ceramic capacitor, rated for at least 25 V, must be connected from each output to its corresponding bootstrap input. Specifically, one 220-nF capacitor must be connected from xOUTP to BSxx, and one 220-nF capacitor must be connected from xOUTN to BSxx. (See the application circuit diagram in [Figure 25](#).)

The bootstrap capacitors connected between the BSxx pins and corresponding output function as a floating power supply for the high-side N-channel power MOSFET gate drive circuitry. During each high-side switching cycle, the bootstrap capacitors hold the gate-to-source voltage high enough to keep the high-side MOSFETs turned on.

## VCLAMP Capacitors

To ensure that the maximum gate-to-source voltage for the NMOS output transistors is not exceeded, two internal regulators clamp the gate voltage. Two 1- $\mu\text{F}$  capacitors must be connected from VCLAMPL and VCLAMP<sub>R</sub> to ground and must be rated for at least 16 V. The voltages at the VCLAMPx terminals may vary with  $V_{\text{CC}}$  and may not be used for powering any other circuitry.

## Internal Regulated 4-V Supply (VREG)

The VREG terminal (pin 10) is the output of an internally generated 4-V supply, used for the oscillator, preamplifier, and gain control circuitry. It requires a 10-nF capacitor, placed close to the pin, to keep the regulator stable.

This regulated voltage can be used to control GAIN0, GAIN1, MSTR/ $\overline{\text{SLV}}$ , and MUTE terminals, but should not be used to drive external circuitry.

## VBYP Capacitor Selection

The internal bias generator (VBYP) nominally provides a 1.25-V internal bias for the preamplifier stages. The external input capacitors and this internal reference allow the inputs to be biased within the optimal common-mode range of the input preamplifiers.

The selection of the capacitor value on the VBYP terminal is critical for achieving the best device performance. During power up or recovery from the shutdown state, the VBYP capacitor determines the rate at which the amplifier starts up. When the voltage on the VBYP capacitor equals VBYP, the device starts a 16.4-ms timer. When this timer completes, the outputs start switching. The charge rate of the capacitor is calculated using the standard charging formula for a capacitor,  $I = C \times dV/dT$ . The charge current is nominally equal to 250 $\mu\text{A}$  and  $dV$  is equal to VBYP. For example, a 1- $\mu\text{F}$  capacitor on VBYP would take 5 ms to reach the value of VBYP and begin a 16.4-ms count before the outputs turn on. This equates to a turn-on time of <30 ms for a 1- $\mu\text{F}$  capacitor on the VBYP terminal.

A secondary function of the VBYP capacitor is to filter high-frequency noise on the internal 1.25-V bias generator. A value of at least 0.47 $\mu\text{F}$  is recommended for the VBYP capacitor. For the best power-up and shutdown pop performance, the VBYP capacitor should be greater than or equal to the input capacitors.

### ROSC Resistor Selection

The resistor connected to the ROSC terminal controls the class-D output switching frequency using [Equation 4](#):

$$F_{\text{OSC}} = \frac{1}{2 \times \text{ROSC} \times \text{COSC}} \quad (4)$$

COSC is an internal capacitor that is nominally equal to 20 pF. Variation over process and temperature can result in a  $\pm 15\%$  change in this capacitor value.

For example, if ROSC is fixed at 100 k $\Omega$ , the frequency from device to device with this fixed resistance could vary from 217 kHz to 294 kHz with a 15% variation in the internal COSC capacitor. The tolerance of the ROSC resistor should also be considered to determine the range of expected switching frequencies from device to device. It is recommended that 1% tolerance resistors be used.

### Differential Input

The differential input stage of the amplifier cancels any noise that appears on both input lines of the channel. To use the TPA3106D1 with a differential source, connect the positive lead of the audio source to the INP input and the negative lead from the audio source to the INN input. To use the TPA3106D1 with a single-ended source, ac ground the INP or INN input through a capacitor equal in value to the input capacitor on INN or INP and apply the audio source to either input. In a single-ended input application, the unused input should be ac grounded at the audio source instead of at the device input for best noise performance.

### SHUTDOWN OPERATION

The TPA3106D1 employs a shutdown mode of operation designed to reduce supply current ( $I_{\text{CC}}$ ) to the absolute minimum level during periods of nonuse for power conservation. The SHUTDOWN input terminal should be held high (see specification table for trip point) during normal operation when the amplifier is in use. Pulling SHUTDOWN low causes the outputs to mute and the amplifier to enter a low-current state. Never leave SHUTDOWN unconnected, because amplifier operation would be unpredictable.

For the best power-off pop performance, place the amplifier in the shutdown or mute mode prior to removing the power supply voltage.

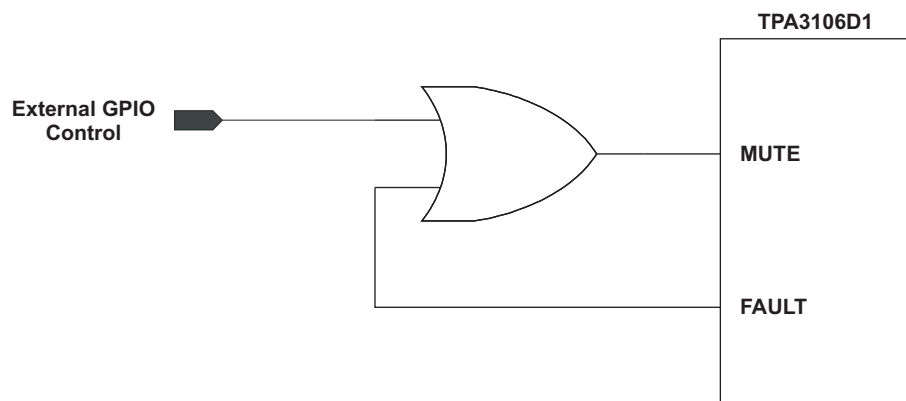
## MUTE OPERATION

The MUTE pin is an input for controlling the output state of the TPA3106D1. A logic high on this terminal disables the outputs. A logic low on this pin enables the outputs. This terminal may be used as a quick disable/enable of outputs when changing channels on a television or transitioning between different audio sources.

The MUTE terminal should never be left floating. For power conservation, the  $\overline{\text{SHUTDOWN}}$  terminal should be used to reduce the quiescent current to the absolute minimum level.

The MUTE terminal can also be used with the FAULT output to automatically recover from a short-circuit event. When a short-circuit event occurs, the FAULT terminal transitions high indicating a short-circuit has been detected. When directly connected to MUTE, the MUTE terminal transitions high, and clears the internal fault flag. This causes the FAULT terminal to cycle low, and normal device operation resumes if the short-circuit is removed from the output. If a short remains at the output, the cycle continues until the short is removed.

If external MUTE control is desired, and automatic recovery from a short-circuit event is also desired, an OR gate can be used to combine the functionality of the FAULT output and external MUTE control, see [Figure 33](#).



**Figure 33. External MUTE Control**

## MSTR/ $\overline{\text{SLV}}$ and SYNC operation

The MSTR/ $\overline{\text{SLV}}$  and SYNC terminals can be used to synchronize the frequency of the class-D output switching when using multiple amplifiers in a single application. When the MSTR/ $\overline{\text{SLV}}$  terminal is high, the output switching frequency is determined by the selection of the resistor connected to the ROOSC terminal (see ROOSC Resistor Selection). The SYNC terminal becomes an output in this mode, and the frequency of this output is also determined by the selection of the ROOSC resistor. This TTL compatible, push-pull output can be connected to other TPA310X devices such as TPA3100D2, configured in slave mode. The output switching is synchronized to avoid beat frequencies that could occur in the audio band when two class-D amplifiers in the same system are switching at slightly different frequencies.

When the MSTR/ $\overline{\text{SLV}}$  terminal is low, the output switching frequency is determined by the incoming square wave on the SYNC input. The SYNC terminal becomes an input in this mode and accepts a TTL compatible square wave from another TPA310X audio amplifier configured in the master mode or from an external GPIO. If connecting to an external GPIO, recommended frequencies are 200 kHz to 300 kHz for proper device operation, and the maximum amplitude is 4 V.

The sync drive on the TPA3106D1 has been improved relative to other TPA310X devices, so please use the TPA3106D1 as the MASTER when connected in synchronous operation with other device of the TPA310X family.

## USING LOW-ESR CAPACITORS

Low-ESR capacitors are recommended throughout this application section. A real (as opposed to ideal) capacitor can be modeled simply as a resistor in series with an ideal capacitor. The voltage drop across this resistor minimizes the beneficial effects of the capacitor in the circuit. The lower the equivalent value of this resistance, the more the real capacitor behaves like an ideal capacitor.

## SHORT-CIRCUIT PROTECTION AND AUTOMATIC RECOVERY FEATURE

The TPA3106D1 has short-circuit protection circuitry on the outputs that prevents damage to the device during output-to-output shorts, output-to-GND shorts, and output-to- $V_{CC}$  shorts. When a short circuit is detected on the outputs, the part immediately disables the output drive. This is a latched fault and must be reset by cycling the voltage on the SHUTDOWN pin or MUTE pin. This clears the short-circuit flag and allows for normal operation if the short was removed. If the short was not removed, the protection circuitry again activates.

The FAULT terminal can be used for automatic recovery from a short-circuit event, or used to monitor the status with an external GPIO. For automatic recovery from a short-circuit event, connect the FAULT terminal directly to the MUTE terminal. When a short-circuit event occurs, the FAULT terminal transitions high indicating a short-circuit has been detected. When directly connected to MUTE, the MUTE terminal transitions high, and clears the internal fault flag. This causes the FAULT terminal to cycle low, and normal device operation resumes if the short-circuit is removed from the output. If a short remains at the output, the cycle continues until the short is removed. If external MUTE control is desired, and automatic recovery from a short-circuit event is also desired, an OR gate can be used to combine the functionality of the FAULT output and external MUTE control, see [Figure 33](#).

## THERMAL PROTECTION

Thermal protection on the TPA3106D1 prevents damage to the device when the internal die temperature exceeds 150°C. There is a  $\pm 15^\circ\text{C}$  tolerance on this trip point from device to device. Once the die temperature exceeds the thermal set point, the device enters into the shutdown state and the outputs are disabled. This is not a latched fault. The thermal fault is cleared once the temperature of the die is reduced by 30°C. The device begins normal operation at this point with no external system interaction.

## PRINTED-CIRCUIT BOARD (PCB) LAYOUT GENERAL GUIDELINES

Because the TPA3106D1 is a class-D amplifier that switches at a high frequency, the layout of the printed-circuit board (PCB) should be optimized according to the following guidelines for the best possible performance.

- Decoupling capacitors—The high-frequency 1- $\mu$ F decoupling capacitors should be placed as close to the PVCC and AVCC terminals as possible. The VBYP capacitor, VREG capacitor, and VCLAMP capacitor should be placed near the TPA3106D1 on the PVCCL, PVCCR, and AVCC.
- Grounding—The AVCC decoupling capacitor, VREG capacitor, VBYP capacitor, and ROsc resistor should each be grounded to analog ground. Analog ground and power ground should be connected at the thermal pad, which should be used as a central ground connection or star ground for the TPA3106D1.
- Output filter—The ferrite EMI filter (if used) should be placed as close to the output terminals as possible for the best EMI performance. The LC filter should be placed close to the outputs.

For an example layout, see the TPA3106D1 Evaluation Module User Manual, (SLOU191). Both the EVM user manual and the thermal pad application note are available on the TI Web site at <http://www.ti.com>.

## BASIC MEASUREMENT SYSTEM

This application note focuses on methods that use the basic equipment listed below:

- Audio analyzer or spectrum analyzer
- Digital multimeter (DMM)
- Oscilloscope
- Twisted-pair wires
- Signal generator
- Power resistor(s)
- Linear regulated power supply
- Filter components
- EVM or other complete audio circuit

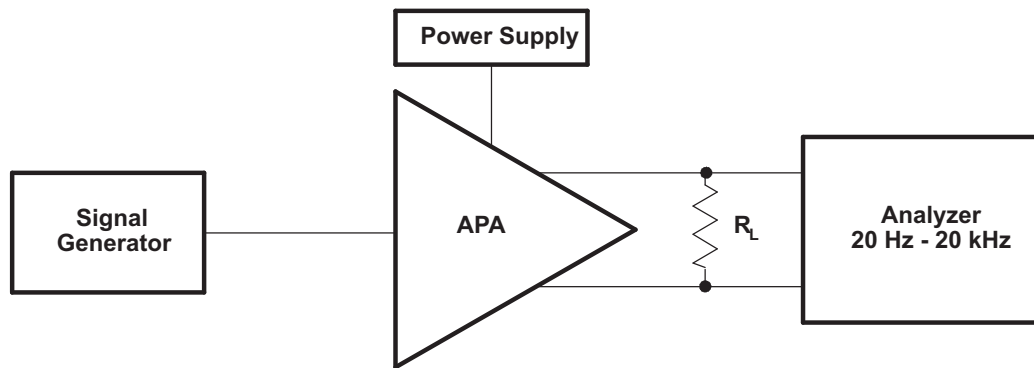
Figure 34 shows the block diagrams of basic measurement systems for class-AB and class-D amplifiers. A sine wave is normally used as the input signal because it consists of the fundamental frequency only (no other harmonics are present). An analyzer is then connected to the APA output to measure the voltage output. The analyzer must be capable of measuring the entire audio bandwidth. A regulated dc power supply is used to reduce the noise and distortion injected into the APA through the power pins. A System Two audio measurement system (AP-II) (Reference 1) by Audio Precision includes the signal generator and analyzer in one package.

The generator output and amplifier input must be ac-coupled. However, the EVMs already have the ac-coupling capacitors, ( $C_{IN}$ ), so no additional coupling is required. The generator output impedance should be low to avoid attenuating the test signal, and is important because the input resistance of PAs is not high. Conversely, the analyzer-input impedance should be high. The output resistance,  $R_{OUT}$ , of the PA is normally in the hundreds of milliohms and can be ignored for all but the power-related calculations.

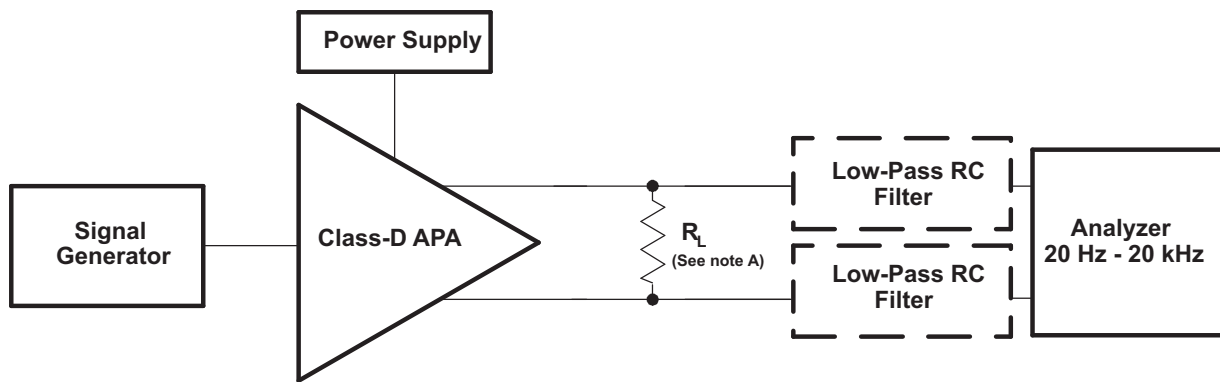
Figure 34(a) shows a class-AB amplifier system. It takes an analog signal input and produces an analog signal output. This amplifier circuit can be directly connected to the AP-II or other analyzer input.

This is not true of the class-D amplifier system shown in Figure 34(b), which requires low-pass filters in most cases in order to measure the audio output waveforms. This is because it takes an analog input signal and converts it into a pulse-width modulated (PWM) output signal that is not accurately processed by some analyzers.





(a) Basic Class-AB



(b) Filter-Free and Traditional Class-D

A. For efficiency measurements with filter-free Class-D,  $R_L$  should be an inductive load like a speaker.

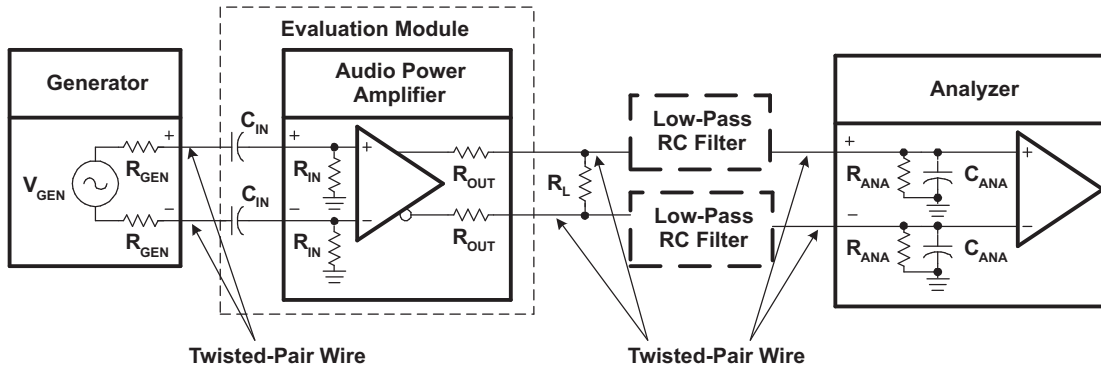
**Figure 34. Audio Measurement Systems**

The device uses a modulation scheme that does not require an output filter for operation, but they do sometimes require an RC low-pass filter when making measurements. This is because some analyzer inputs cannot accurately process the rapidly changing square-wave output and therefore record an extremely high level of distortion. The RC low-pass measurement filter is used to remove the modulated waveforms so the analyzer can measure the output sine wave.

## DIFFERENTIAL INPUT AND BTL OUTPUT

All of the class-D APAs and many class-AB APAs have differential inputs and bridge-tied load (BTL) outputs. Differential inputs have two input pins per channel and amplify the difference in voltage between the pins. Differential inputs reduce the common-mode noise and distortion of the input circuit. BTL is a term commonly used in audio to describe differential outputs. BTL outputs have two output pins providing voltages that are 180 degrees out of phase. The load is connected between these pins. BTL configuration has the added benefits of quadrupling the output power to the load and eliminating a dc blocking capacitor.

A block diagram of the measurement circuit is shown in Figure 35. The differential input is a balanced input, meaning the positive (+) and negative (-) pins have the same impedance to ground. Similarly, the BTL output equates to a balanced output.



**Figure 35. Differential Input, BTL Output Measurement Circuit**

The generator should have balanced outputs, and the signal should be balanced for best results. An unbalanced output can be used, but it may create a ground loop that affects the measurement accuracy. The analyzer must also have balanced inputs for the system to be fully balanced, thereby cancelling out any common-mode noise in the circuit and providing the most accurate measurement.

The following general rules should be followed when connecting to APAs with differential inputs and BTL outputs:

- Use a balanced source to supply the input signal.
- Use an analyzer with balanced inputs.
- Use twisted-pair wire for all connections.
- Use shielding when the system environment is noisy.
- Ensure that the cables from the power supply to the APA, and from the APA to the load, can handle the large currents (see Table 2).

Table 2 shows the recommended wire size for the power supply and load cables of the APA system. The real concern is the dc or ac power loss that occurs as the current flows through the cable. These recommendations are based on 12-inch long wire with a 20-kHz sine-wave signal at 25°C.

**Table 2. Recommended Minimum Wire Size for Power Cables**

P <sub>OUT</sub> (W)	R <sub>L</sub> (Ω)	AWG Size		DC POWER LOSS (MW)		AC POWER LOSS (MW)	
10	4	18	22	16	40	18	42
2	4	18	22	3.2	8	3.7	8.5
1	8	22	28	2	8	2.1	8.1
< 0.75	8	22	28	1.5	6.1	1.6	6.2

## CLASS-D RC LOW-PASS FILTER

An RC filter is used to reduce the square-wave output when the analyzer inputs cannot process the pulse-width modulated class-D output waveform. This filter has little effect on the measurement accuracy because the cutoff frequency is set above the audio band. The high frequency of the square wave has negligible impact on measurement accuracy because it is well above the audible frequency range, and the speaker cone cannot respond at such a fast rate. The RC filter is not required when an LC low-pass filter is used, such as with the class-D APAs that employ the traditional modulation scheme (TPA032D0x, TPA005Dxx).

The component values of the RC filter are selected using the equivalent output circuit as shown in Figure 36.  $R_L$  is the load impedance that the APA is driving for the test. The analyzer input impedance specifications should be available and substituted for  $R_{ANA}$  and  $C_{ANA}$ . The filter components,  $R_{FILT}$  and  $C_{FILT}$ , can then be derived for the system. The filter should be grounded to the APA near the output ground pins or at the power supply ground pin to minimize ground loops.

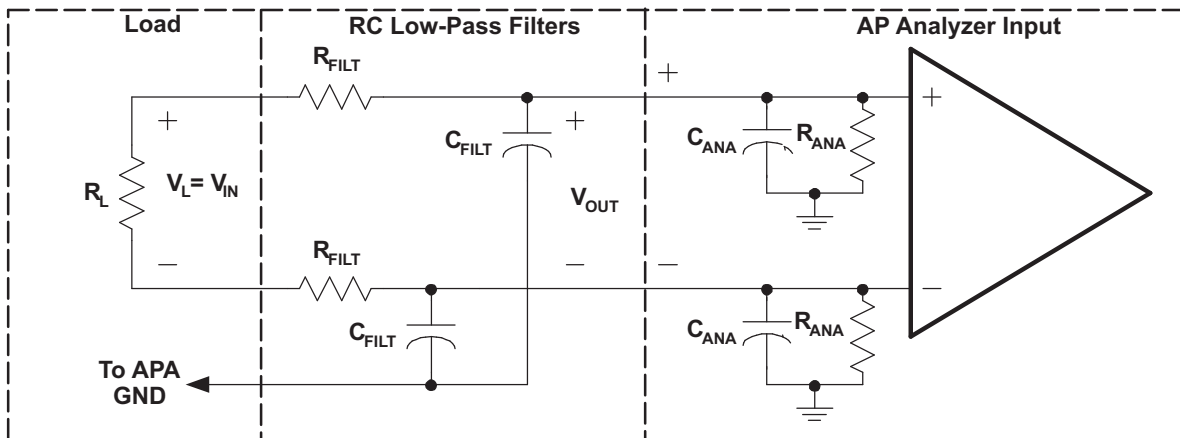


Figure 36. Measurement Low-Pass Filter Derivation Circuit-Class-D APAs

The transfer function for this circuit is shown in Equation 5 where  $\omega_O = R_{EQ}C_{EQ}$ ,  $R_{EQ} = R_{FILT} \parallel R_{ANA}$  and  $C_{EQ} = (C_{FILT} + C_{ANA})$ . The filter frequency should be set above  $f_{MAX}$ , the highest frequency of the measurement bandwidth, to avoid attenuating the audio signal. Equation 6 provides this cutoff frequency,  $f_C$ . The value of  $R_{FILT}$  must be chosen large enough to minimize current that is shunted from the load, yet small enough to minimize the attenuation of the analyzer-input voltage through the voltage divider formed by  $R_{FILT}$  and  $R_{ANA}$ . A general rule is that  $R_{FILT}$  should be small ( $\sim 100 \Omega$ ) for most measurements. This reduces the measurement error to less than 1% for  $R_{ANA} \geq 10 \text{ k}\Omega$ .

$$\left( \frac{V_{OUT}}{V_{IN}} \right) = \frac{\left( \frac{R_{ANA}}{R_{ANA} + R_{FILT}} \right)}{1 + j \left( \frac{\omega}{\omega_O} \right)} \quad (5)$$

$$f_C = \sqrt{2} \times f_{max} \quad (6)$$

An exception occurs with the efficiency measurements, where  $R_{FILT}$  must be increased by a factor of ten to reduce the current shunted through the filter.  $C_{FILT}$  must be decreased by a factor of ten to maintain the same cutoff frequency. See Table 3 for the recommended filter component values.

Once  $f_C$  is determined and  $R_{FILT}$  is selected, the filter capacitance is calculated. When the calculated value is not available, it is better to choose a smaller capacitance value to keep  $f_C$  above the minimum desired value calculated in Equation 7.

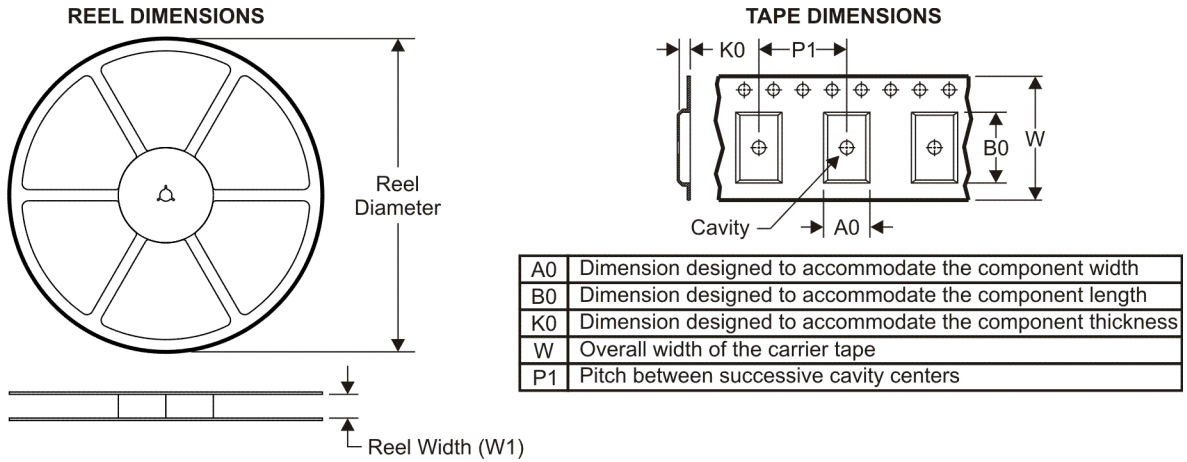
$$C_{\text{FILT}} = \frac{1}{2\pi \times f_c \times R_{\text{FILT}}} \quad (7)$$

Table 3 shows recommended values of  $R_{\text{FILT}}$  and  $C_{\text{FILT}}$  based on common component values. The value of  $f_c$  was originally calculated to be 28 kHz for an  $f_{\text{MAX}}$  of 20 kHz.  $C_{\text{FILT}}$ , however, was calculated to be 57,000 pF, but the nearest values of 56,000 pF and 51,000 pF were not available. A 47,000-pF capacitor was used instead, and  $f_c$  is 34 kHz, which is above the desired value of 28 kHz.

**Table 3. Typical RC Measurement Filter Values**

MEASUREMENT	$R_{\text{FILT}}$	$C_{\text{FILT}}$
Efficiency	1000 $\Omega$	5,600 pF
All other measurements	100 $\Omega$	56,000 pF

**TAPE AND REEL INFORMATION**



**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPA3106D1VFPR	HLQFP	VFP	32	1000	330.0	16.0	10.0	10.0	2.0	12.0	16.0	Q2

**TAPE AND REEL BOX DIMENSIONS**

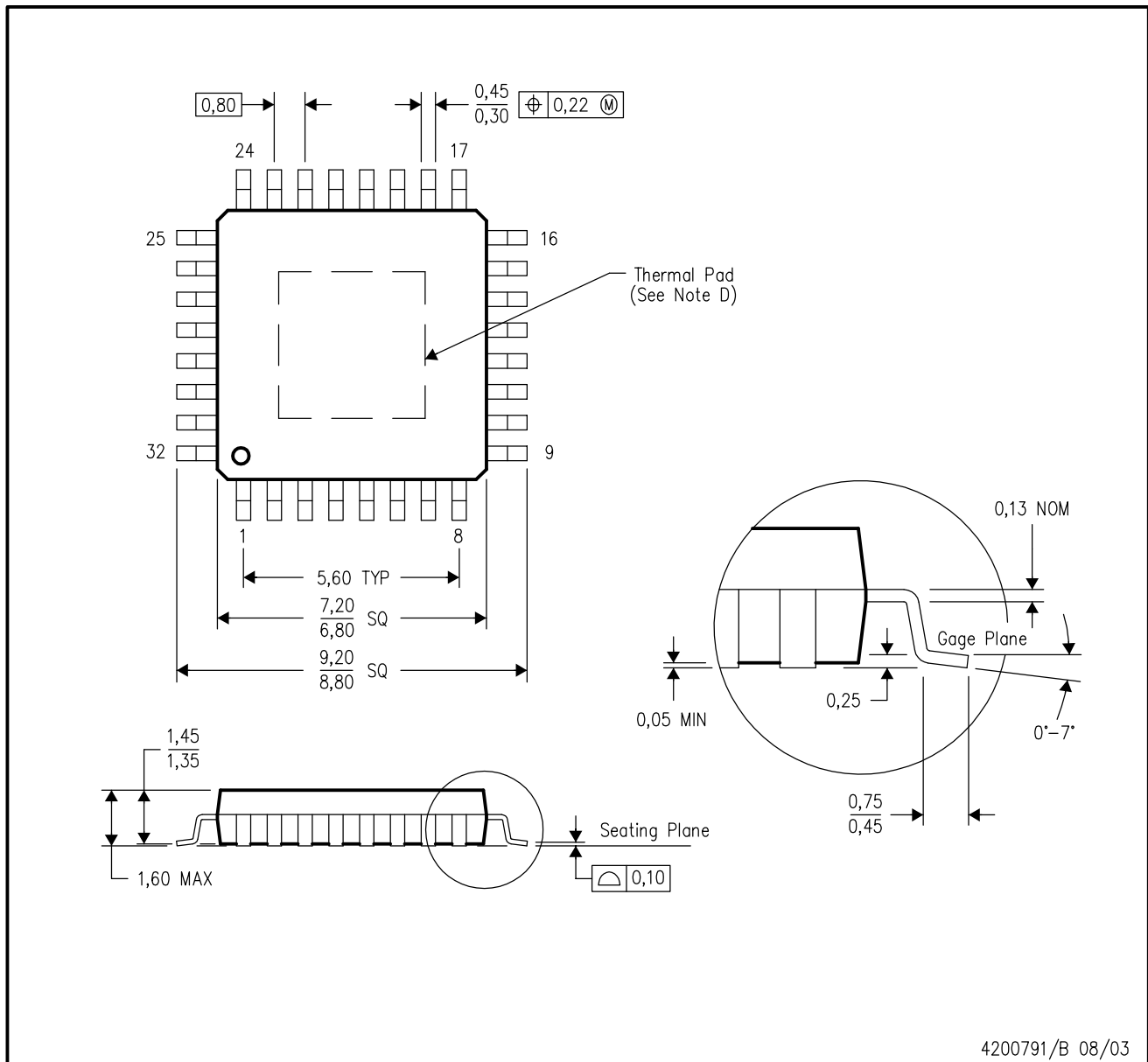


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPA3106D1VFPR	HLQFP	VFP	32	1000	346.0	346.0	33.0

VFP (S-PQFP-G32)

PowerPAD™ PLASTIC QUAD FLATPACK



4200791/B 08/03

- NOTES:
- A. All linear dimensions are in millimeters.
  - B. This drawing is subject to change without notice.
  - C. Body dimensions do not include mold flash or protrusion.
  - D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at [www.ti.com](http://www.ti.com) <<http://www.ti.com>>.
  - E. Falls within JEDEC MS-026
  - F. PowerPAD is a trademark of Texas Instruments Incorporated.

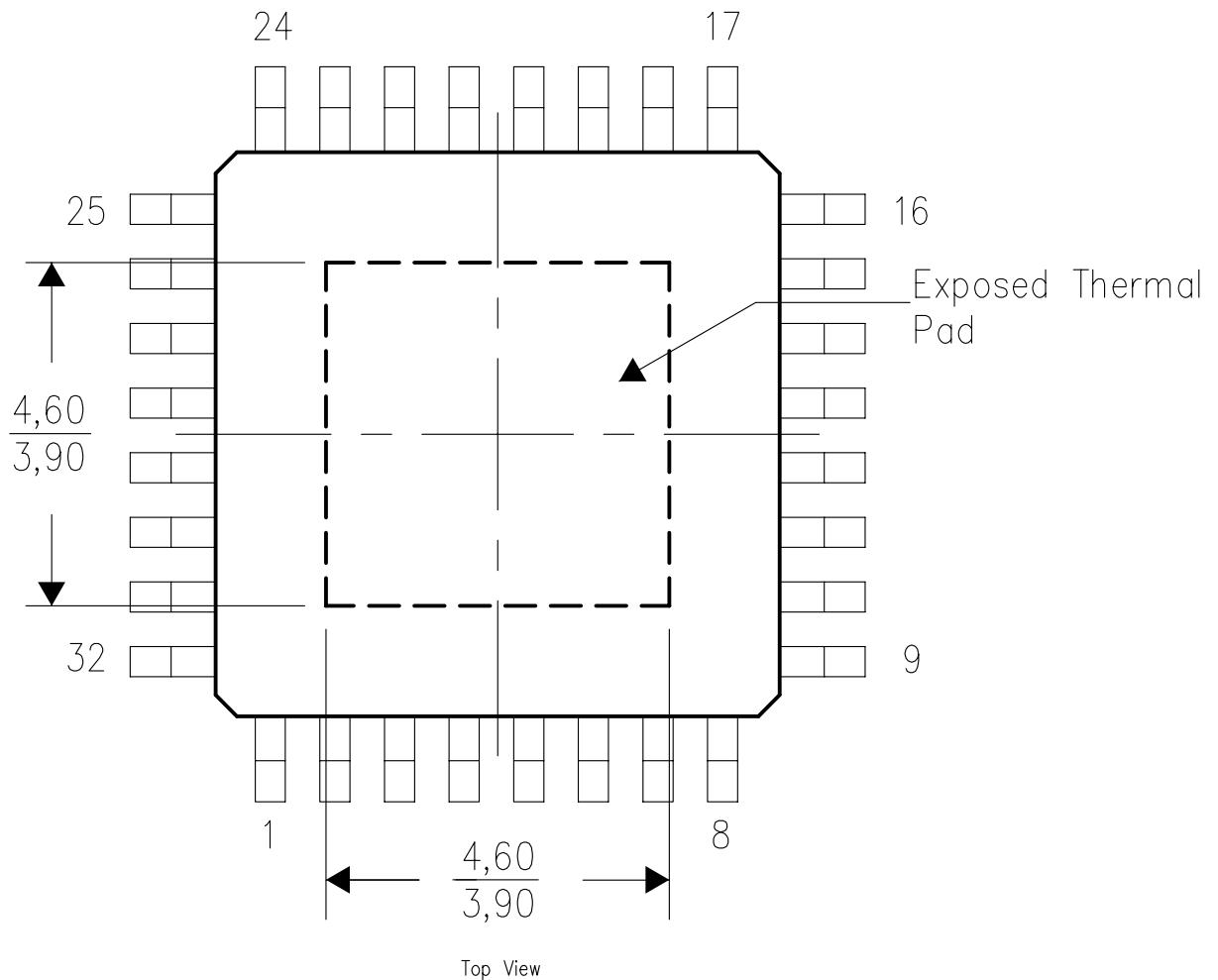
PowerPAD is a trademark of Texas Instruments.

**THERMAL INFORMATION**

This PowerPAD™ package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at [www.ti.com](http://www.ti.com).

The exposed thermal pad dimensions for this package are shown in the following illustration.



NOTE: All linear dimensions are in millimeters

Exposed Thermal Pad Dimensions



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Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265  
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